

# IBR Models and Modeling Needs

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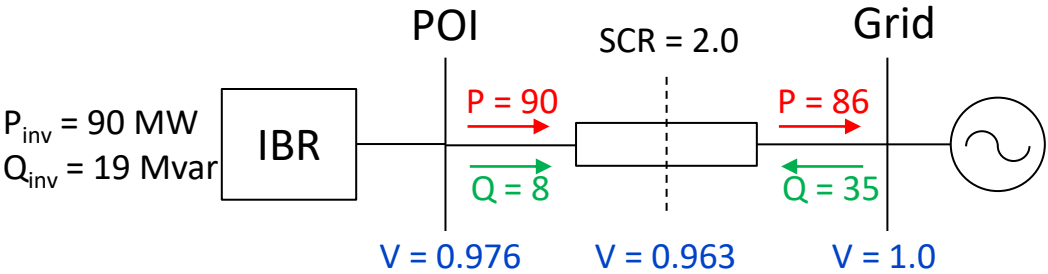
# Power system simulations

- An objective of a simulation:
  - Get visibility and insight regarding dynamic characteristic response of a system
- How are dynamic characteristics represented?
  - Predominantly through use of differential equations that represent the rate at which quantities change.
- How is the above objective achieved?
  - Through integration of differential equations
  - Along with solution of algebraic equations (if present)

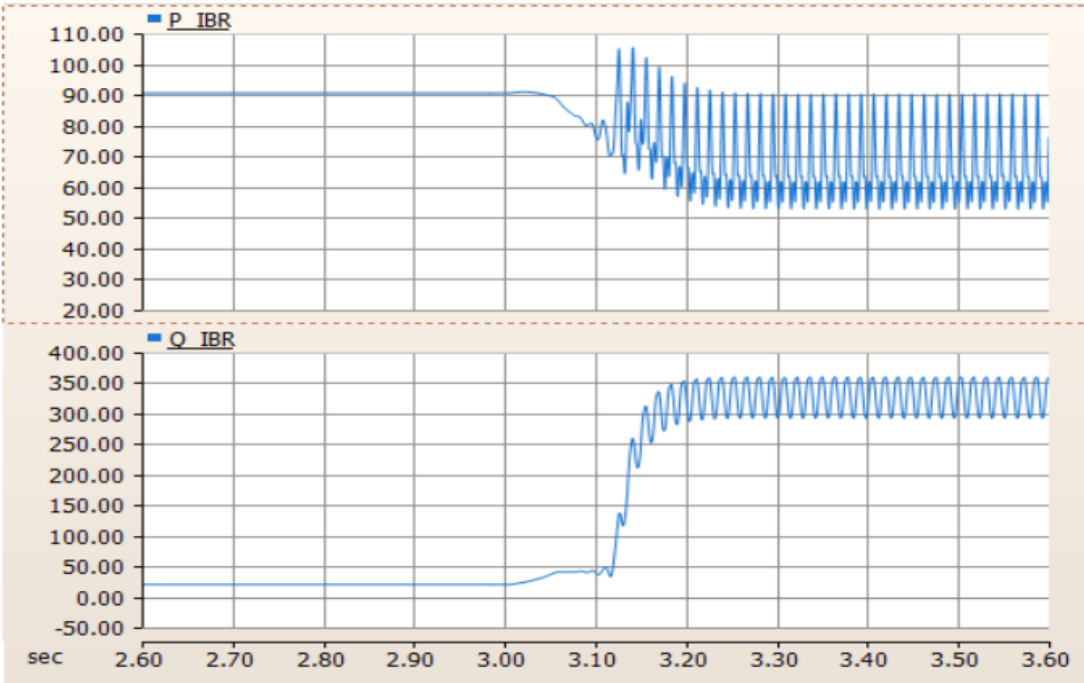
# Objective of a model

- Provide a trend of response of dynamic behavior
- Not advisable to have too strict/tight a set of expectations from a model
  - A lot of uncertainty is present when carrying out a simulation study
- Models across simulation domains may have nuanced differences in implementation in order to provide similar time domain response

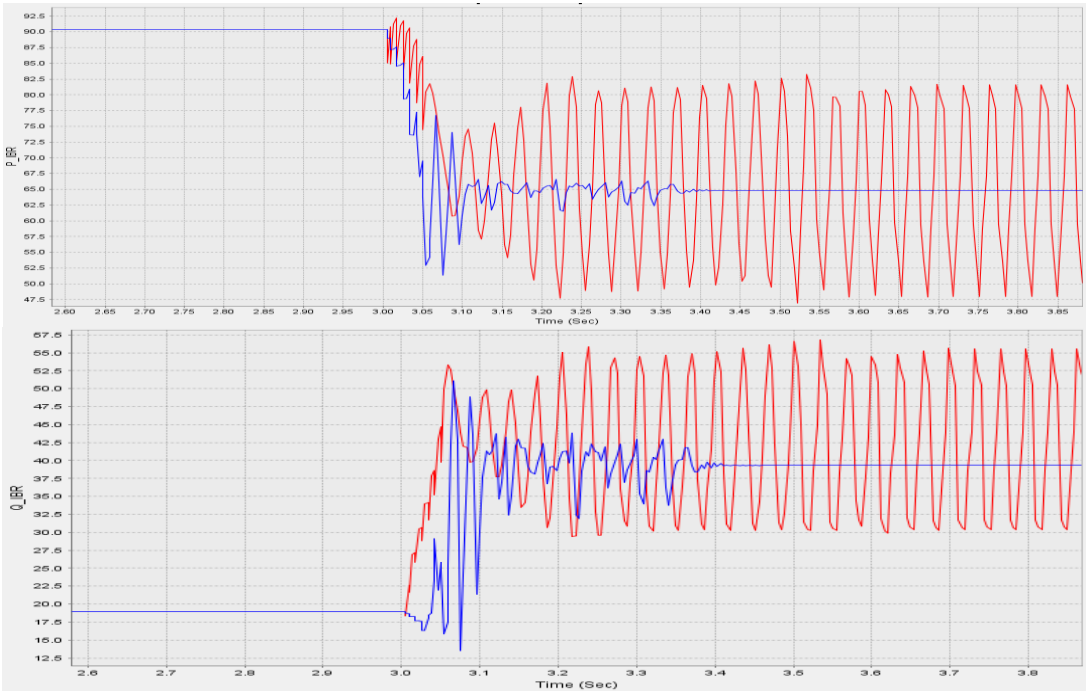
# Consider an example of IBR and low short circuit scenario



Here, if SCR reduces to 1.0, instability results



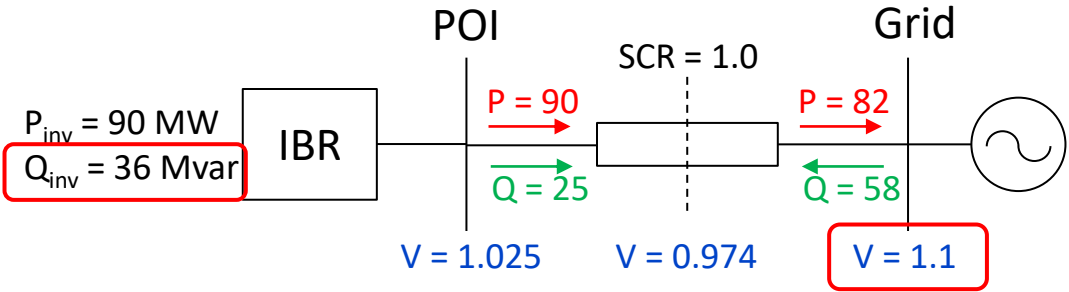
EMT domain



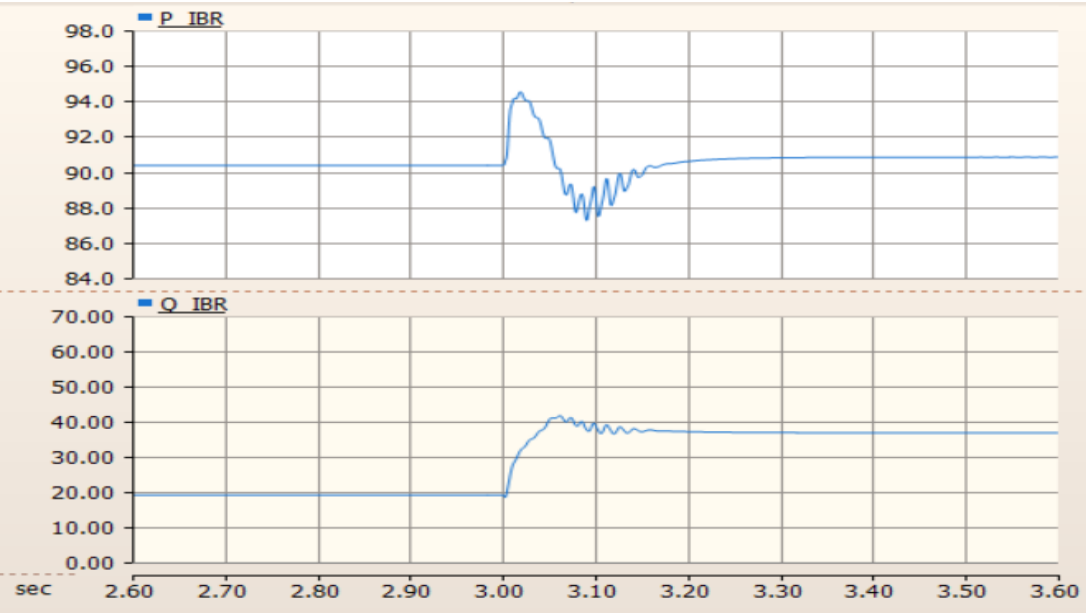
+SEQ domain (old vs new models)

[Details regarding IBR models used](#)

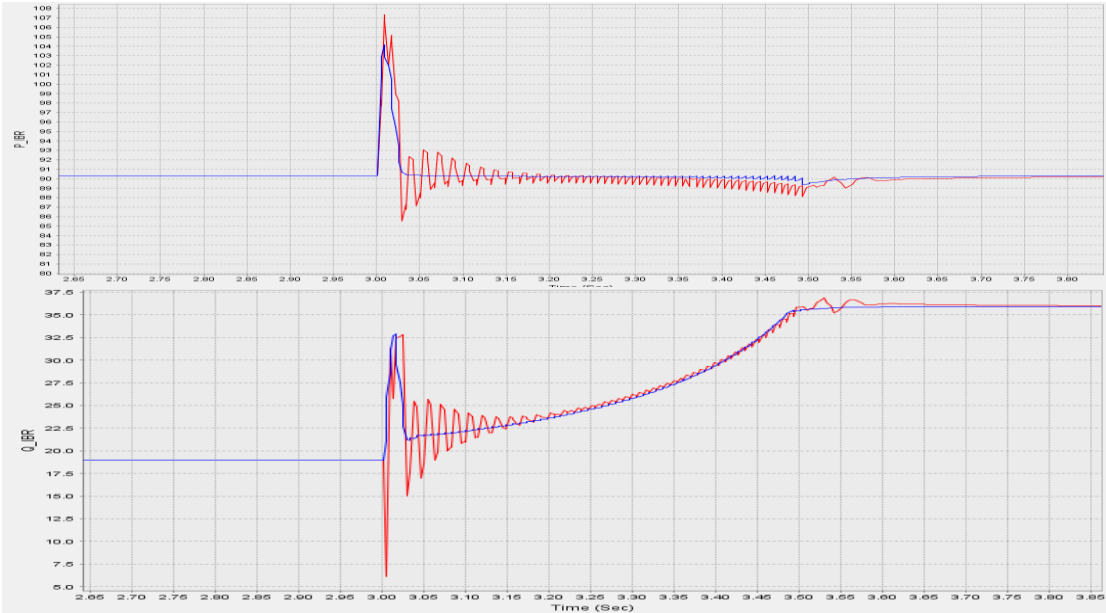
# Consider an example of IBR and low short circuit scenario



Knowing the power flow solution, can help to obtain stability



EMT domain



+SEQ domain (old vs new models)

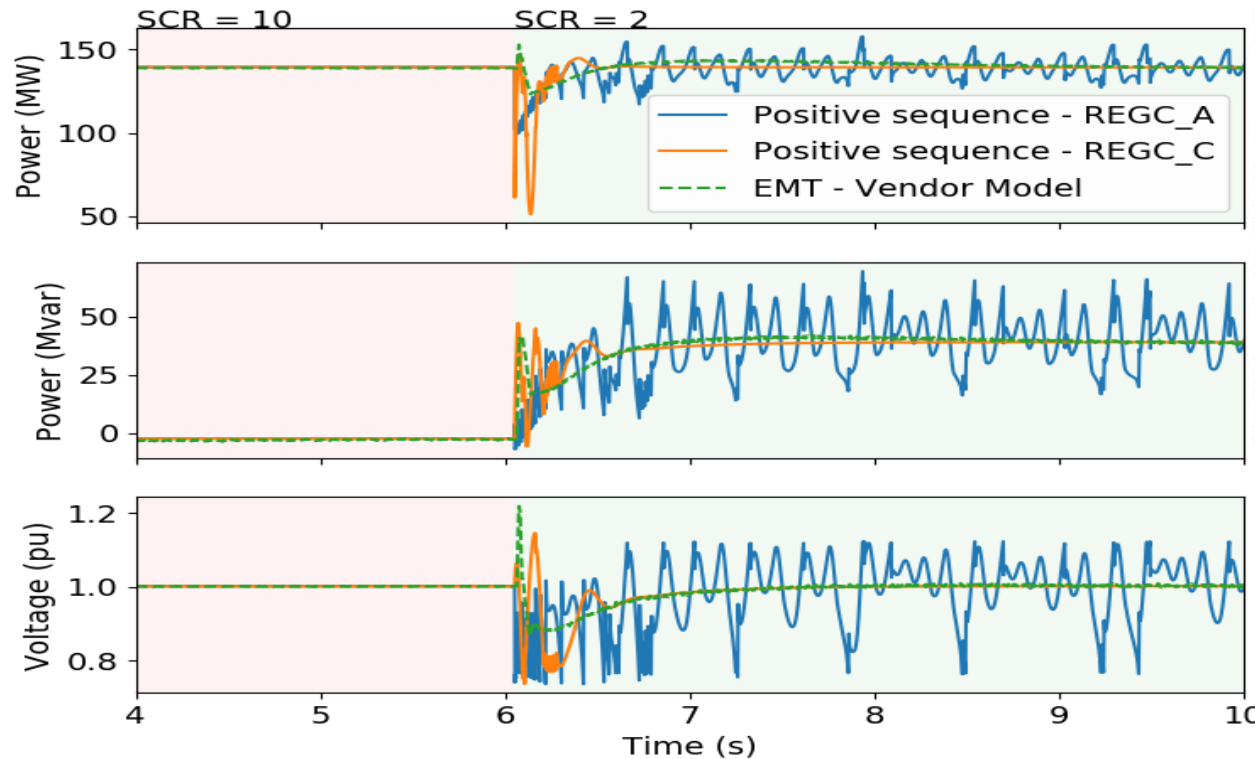
New models still have more room for improvement

# Representation of IBRs in simulation

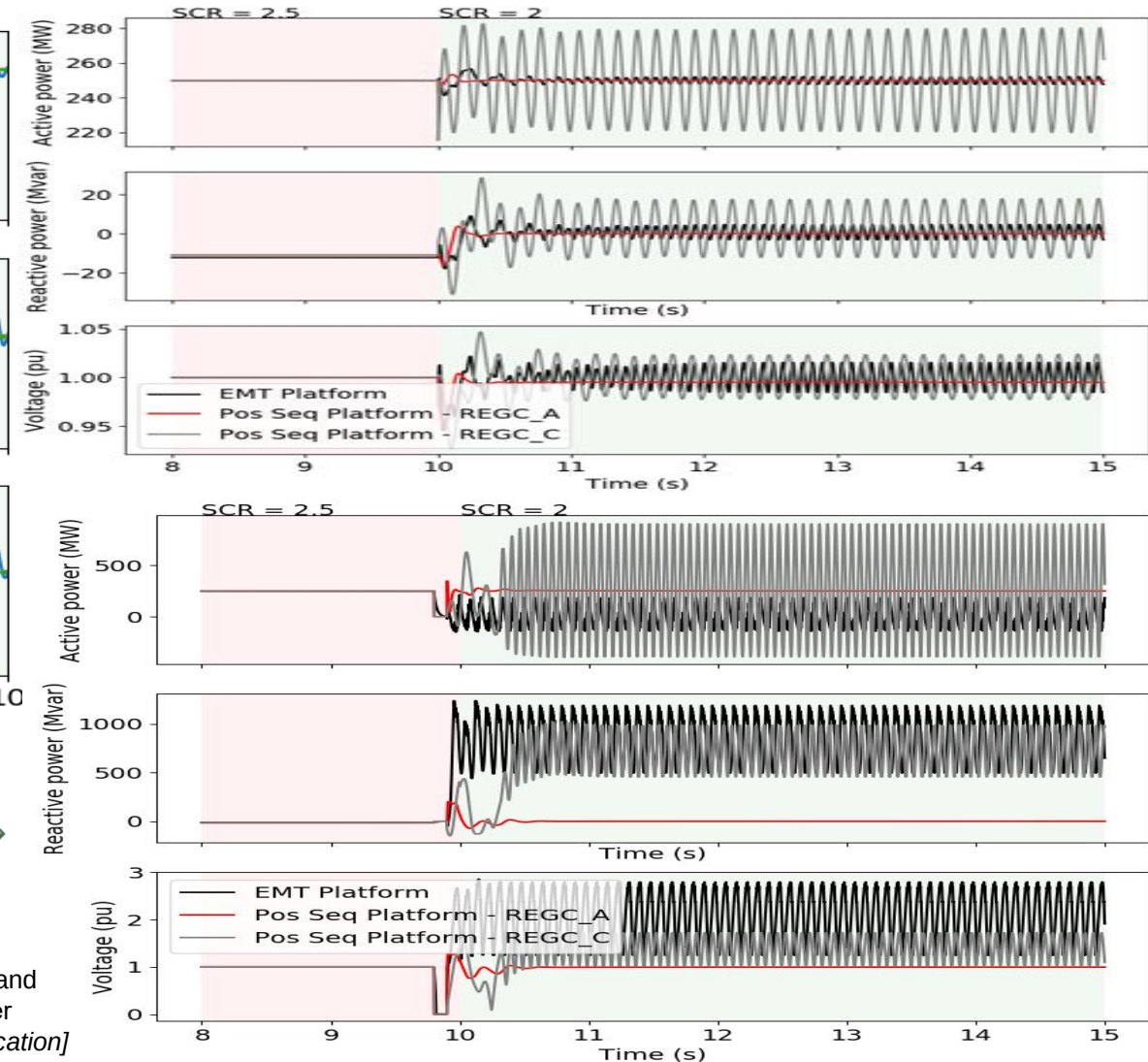
- Every inverter for power system operation is a voltage source inverter
- State of the art interconnection wide simulations (generic and most UDM models available today) represent the inverter as a current source interface:
  - Assumes that current controller and PLL loops are fast
- Maybe we need all IBRs to be represented using a voltage source interface
  - Allows for greater accuracy and characterization of IBR dynamic behavior
  - Allows for representation of current controller and PLL loops



# Beware false positive and false negative results from inaccurate models

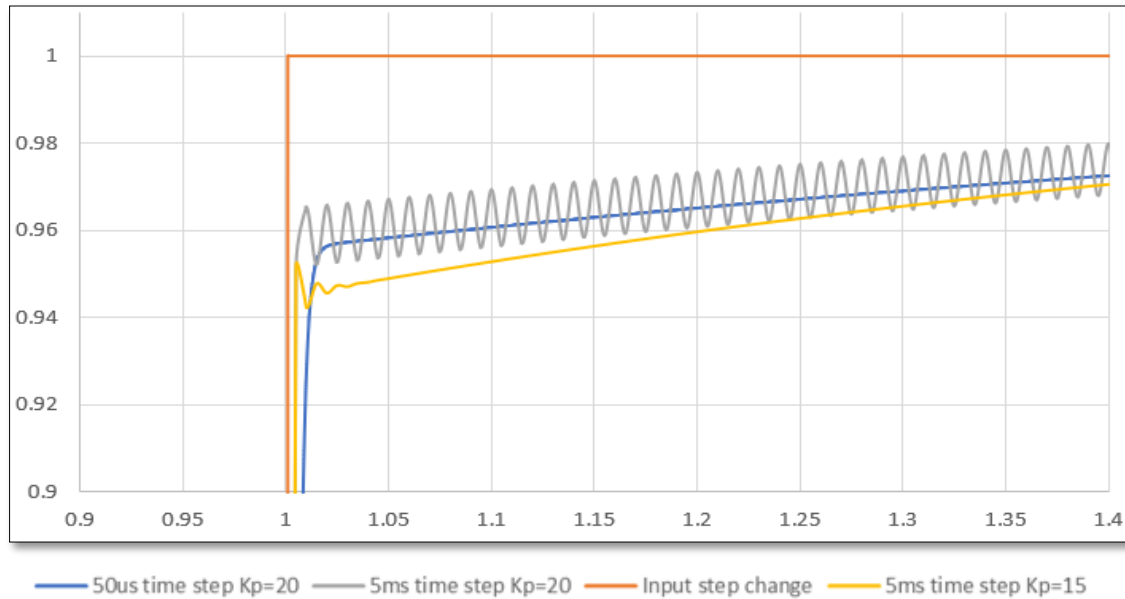


User defined positive sequence model from OEM was unable to show the oscillations

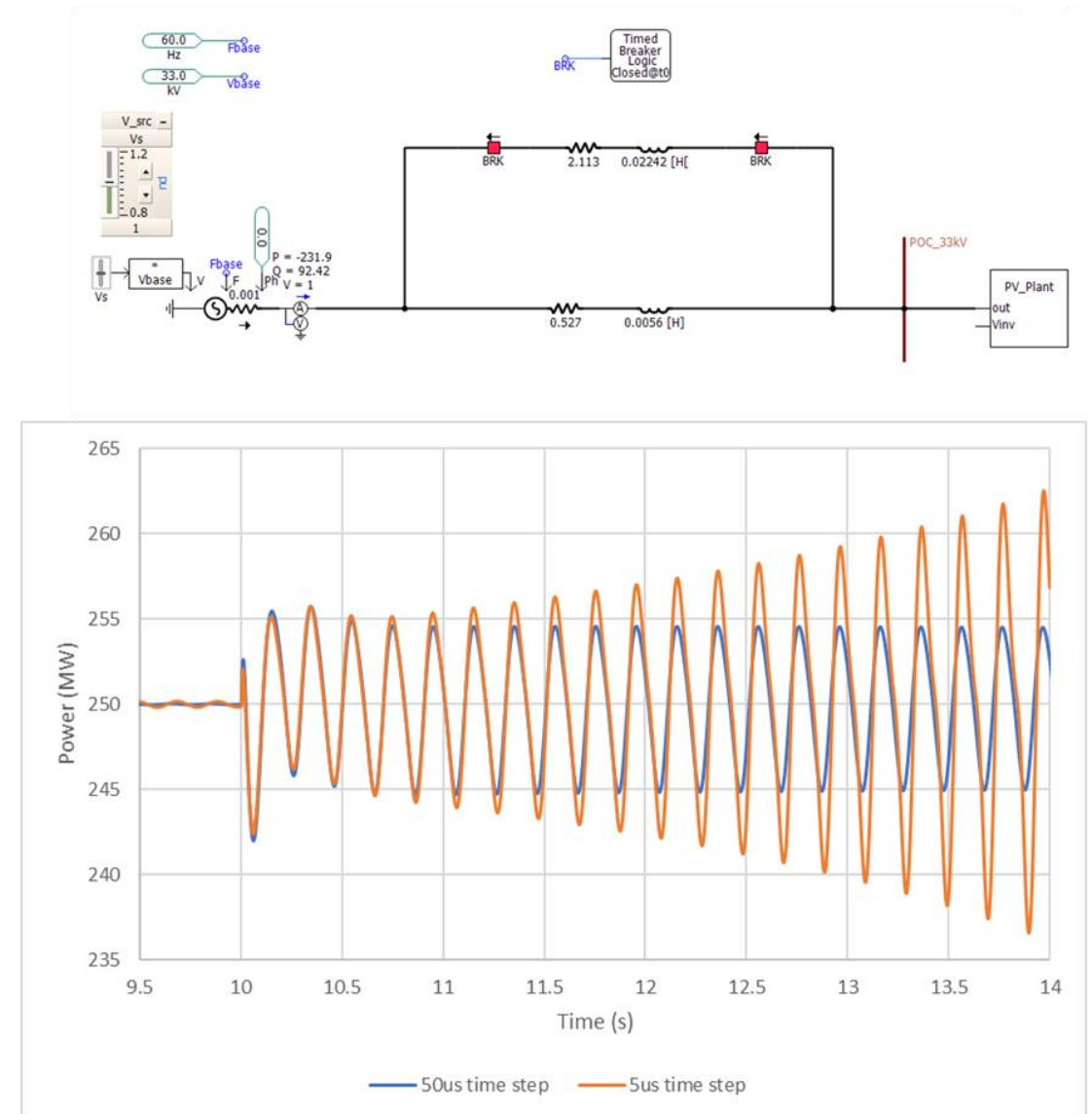


Deepak Ramasubramanian, Xiaoyu Wang, Sachin Goyal, Manjula Dewadasa, Yin Li, Robert J. O'Keefe, and Peter F. Mayer, "Parameterization of Generic Positive Sequence Models to Represent Behavior of Inverter Based Resources in Low Short Circuit Scenarios," *Electric Power Systems Research*, [accepted for publication]

# Parameterization, integration method, and time step

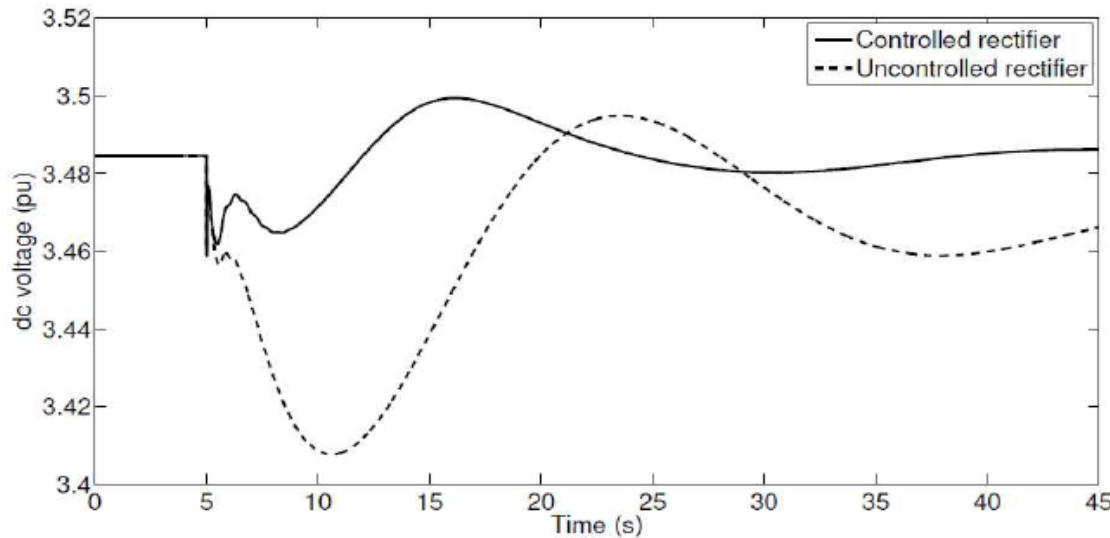
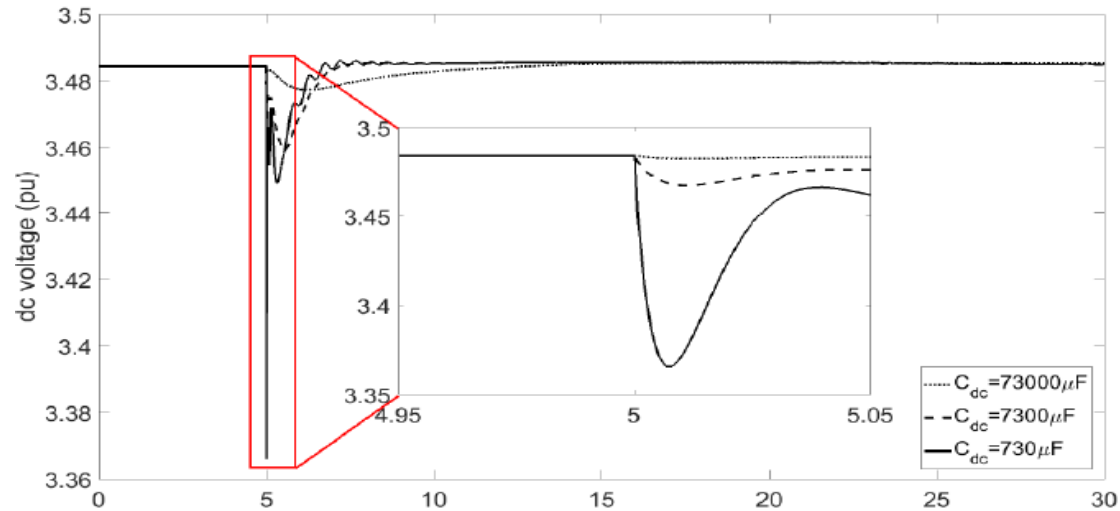


- Value of time step of numerical integration can impact time domain dynamic response
- Method of numerical integration method can have an impact





# Should we represent IBR dc side dynamics?



- It is possible to capture IBR dc side dynamics in a positive sequence model
- Whether it is required to be captured in the model will be known only after detailed studies
  - Keeping in mind that most studies (including EMT) represent controls of one inverter/turbine, and scale appropriately

D. Ramasubramanian and V. Vittal, "Positive sequence model for converter-interfaced synchronous generation with finite dc capacitance," *IEEE Transactions on Power Systems*, vol. 33, no. 3, pp. 3172–3180, 2018

# Model limitation versus simulation domain limitation

- **Present models** in planning base cases (both positive sequence and EMT) have been unable to capture causes of inverter tripping
- Limitation of a model should not be confused with limitation of the simulation domain itself
- Models (such as REGC\_C and other future models) can help bring about added capability that can be leveraged

| Cause of observed behavior              | Simulation domain limitation | Most of today's model incorrectly parameterized | Most of today's model do not represent |                                                                      |
|-----------------------------------------|------------------------------|-------------------------------------------------|----------------------------------------|----------------------------------------------------------------------|
| Unbalanced conditions                   | ✓                            |                                                 |                                        |                                                                      |
| Sub-cycle ac over voltage               | ✓                            |                                                 |                                        |                                                                      |
| Sub-cycle ac over current               | ✓                            |                                                 |                                        |                                                                      |
| Momentary cessation                     |                              | ✓                                               |                                        | Future model can represent as capability exists in simulation domain |
| Error in frequency measurement          |                              | ✓                                               |                                        |                                                                      |
| PLL loss of synchronism                 |                              | ✓                                               |                                        |                                                                      |
| Collector network level under frequency |                              | ✓                                               |                                        |                                                                      |
| Phase jump                              |                              |                                                 | ✓                                      |                                                                      |
| dc reverse current                      |                              |                                                 | ✓                                      |                                                                      |
| dc low voltage                          |                              |                                                 | ✓                                      |                                                                      |
| Plant controller interactions           |                              |                                                 | ✓                                      |                                                                      |

(a) Positive sequence simulation domain

| Cause of observed behavior              | Simulation domain limitation | Most of today's model incorrectly parameterized | Most of today's model do not represent |                                                                      |
|-----------------------------------------|------------------------------|-------------------------------------------------|----------------------------------------|----------------------------------------------------------------------|
| Unbalanced conditions                   |                              | ✓                                               |                                        | Future model can represent as capability exists in simulation domain |
| Sub-cycle ac over voltage               |                              | ✓                                               |                                        |                                                                      |
| Sub-cycle ac over current               |                              | ✓                                               |                                        |                                                                      |
| Momentary cessation                     |                              | ✓                                               |                                        |                                                                      |
| Error in frequency measurement          |                              | ✓                                               |                                        |                                                                      |
| PLL loss of synchronism                 |                              | ✓                                               |                                        |                                                                      |
| Collector network level under frequency |                              | ✓                                               |                                        |                                                                      |
| Phase jump                              |                              |                                                 | ✓                                      |                                                                      |
| dc reverse current                      |                              |                                                 | ✓                                      |                                                                      |
| dc low voltage                          |                              |                                                 | ✓                                      |                                                                      |
| Plant controller interactions           |                              |                                                 | ✓                                      |                                                                      |

(b) EMT simulation domain

*Differentiating between Applicability of Simulation Domains and Inverter Mathematical Models in these Domains.* EPRI. Palo Alto, CA: 2022.3002025063.  
[Online] <https://www.epri.com/research/products/000000003002025063>

# Draft questions for positive sequence model quality check to characterize sufficiency of obtained model

To be discussed with industry and various stakeholders

|                                          |                                                                                                                                                                                           | Yes/No | Comments                                                                                                                                     |
|------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------|----------------------------------------------------------------------------------------------------------------------------------------------|
| RMS/Positive sequence model <sup>1</sup> |                                                                                                                                                                                           |        |                                                                                                                                              |
| 1a                                       | Is the model real code and is the same code used in the EMT model?                                                                                                                        |        | List out any assumptions/modifications made between EMT real code and positive sequence real code (including by-passing of control elements) |
| 1b                                       | Model should be represented using a voltage source interface, even for conventional grid following inverters <sup>2</sup>                                                                 |        |                                                                                                                                              |
| 1c                                       | Model should have a representation of dynamic inner current control loop, if such a control loop is represented in the EMT model of the inverter                                          |        |                                                                                                                                              |
| 1d                                       | Model should have a representation of dynamic of phase locked loop, if such a control loop is represented in the EMT model of inverter <sup>3</sup>                                       |        |                                                                                                                                              |
| 1e                                       | If current output goes above maximum current limit, the model should be capable of limiting the current to the limit at every time step, without losing convergence with network solution |        |                                                                                                                                              |
| 1f                                       | Document any change in values of parameters between EMT and RMS/positive sequence models, with explanation                                                                                |        |                                                                                                                                              |
| 1g                                       | Document any change in control structure (including by-passing any control path) between EMT and RMS/positive sequence models, with explanation and validation                            |        |                                                                                                                                              |
| 1h                                       | For three phase voltage and current, time steps should not be present more than 2 – <u>time</u> steps                                                                                     |        |                                                                                                                                              |
| 1i                                       | Model should be capable of operating in time steps between <u>10ms</u> – 10ms <sup>4</sup>                                                                                                |        |                                                                                                                                              |
| 1j                                       | Does the model represent the dynamics of the source behind the inverter and/or dynamics of the bus?                                                                                       |        |                                                                                                                                              |

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<sup>1</sup> Applicable only for user defined RMS/positive sequence models and not for generic library models

<sup>2</sup> Voltage source interface means that the model is not injecting current directly into the network solution of the simulation solver, but is instead creating either a Thevenin voltage or a Norton current (with low Norton impedance, typically 0.1 – 0.2pu representing the filter impedance)

<sup>3</sup> Exclusion of this feature can be acceptable only if validation report is provided comparing response with EMT model at SCR levels between 1.0 – 2.5 for small signal and large signal events. Additionally, if representation of dynamics are included, they have to be more than a single first order time constant.

<sup>4</sup> Use of higher values of time steps will depend on value of smallest time constant

# Challenges for new modeling practices

- OEMs may require new techniques to write/construct models in simulation software
- Model validation techniques/guidelines may need more rigor
- Application of engineering judgement is extremely important when using models for simulation studies.



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