



National Laboratory
of the Rockies

Data Center Power Systems

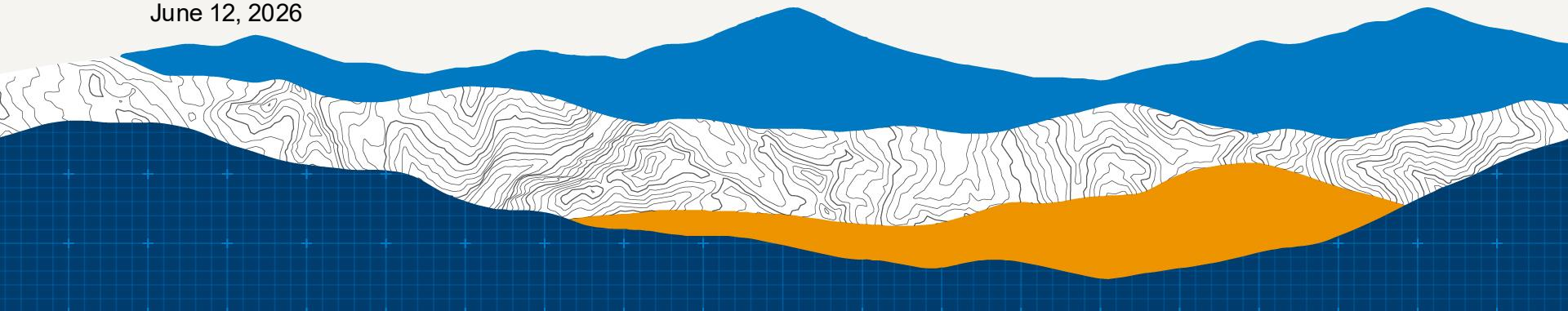
EMT Modeling for Evaluating Converter-Driven Stability Problems and Oscillations

Shahil Shah

Principal Engineer, NLR

ESIG Summer Workshop: Large Load Modeling, Testing, and Interconnection
Requirements

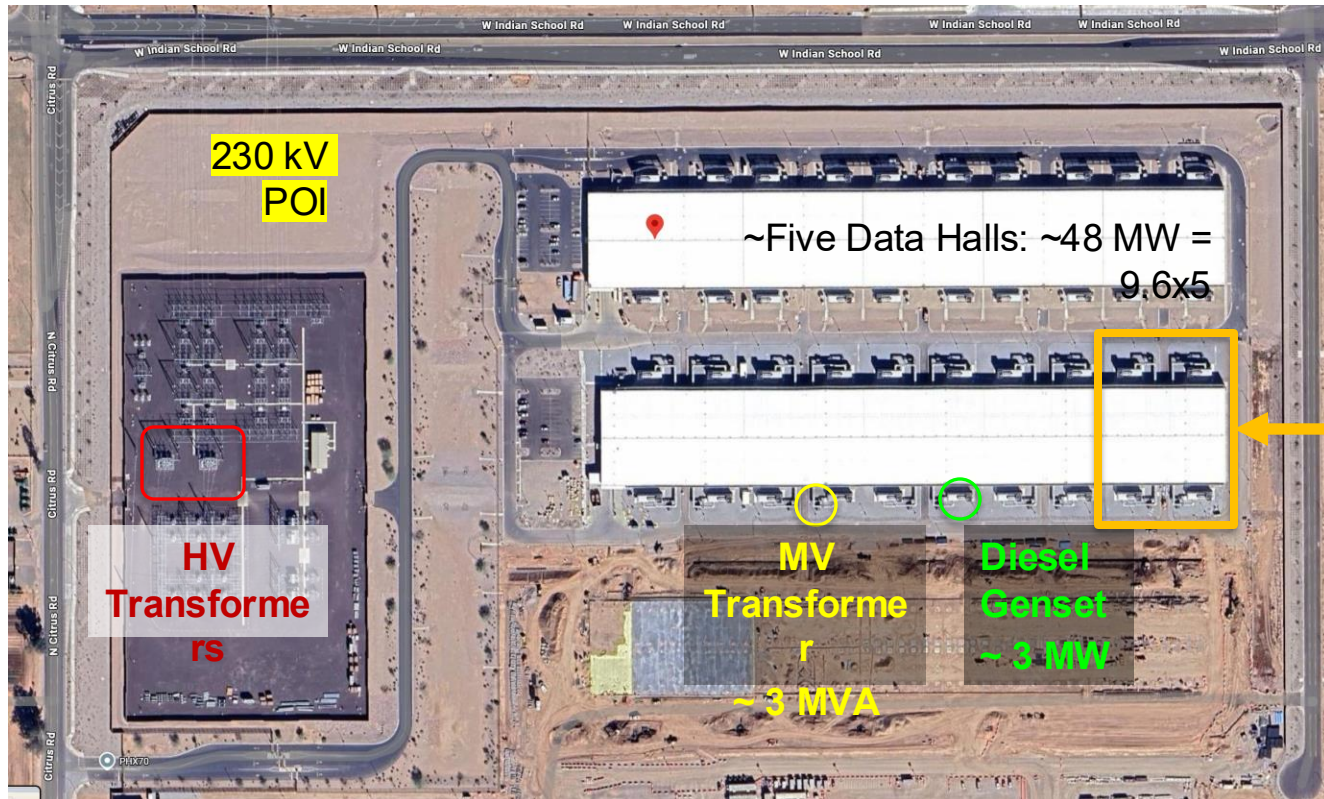
June 12, 2026



Outline

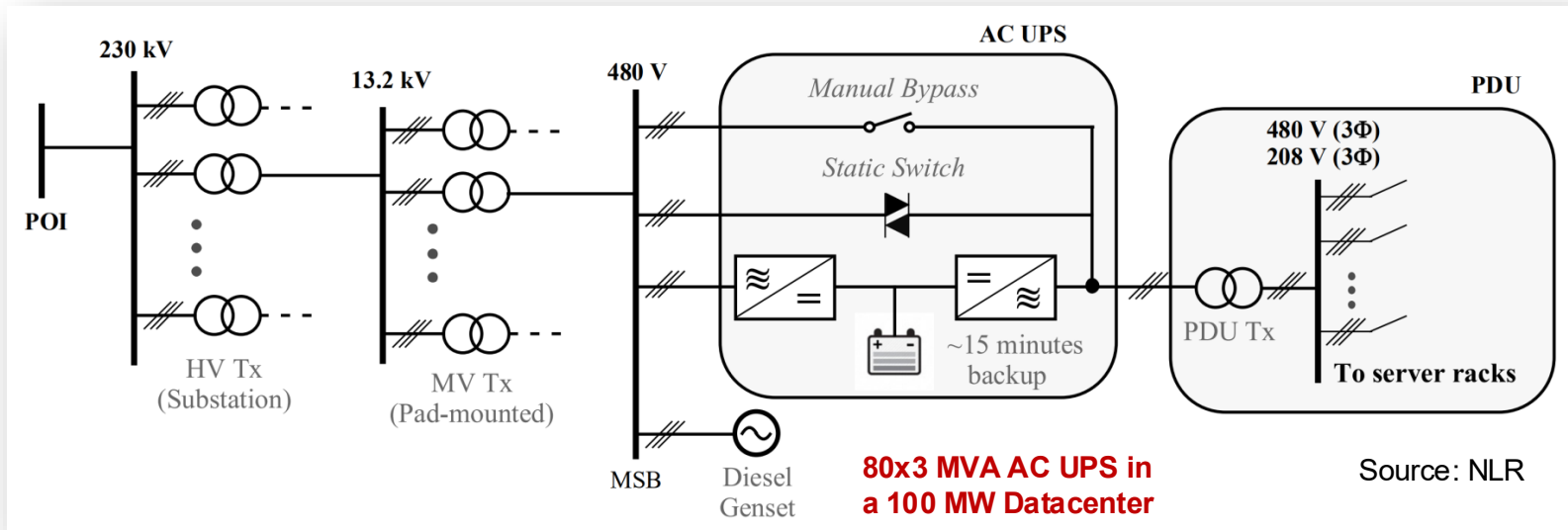
- Factor to Consider for EMT Modeling of Data Centers
 - Data Center Power System Architecture
 - Power Converters in Data Centers that Interface with Grid
 - Operation Modes of AC UPS
- Types of Converter Driven Control Interactions in Data Centers
- EMT PSCAD Model of an IT Rack
 - PSU Based on Single-Phase Totem-Pole Bridgeless PFC Topology
 - Averaging Techniques for Fast EMT Simulation of Data Centers
 - Impedance-Based Stability Analysis

Data Center Near Phoenix, AZ (~100 MW)



- Each building is estimated to have five data halls with around four pods per data hall
- Each pod is estimated to have 2.5 MW of load
- Each pod has one Genset, two AC UPS (N+1 redundancy), and numerous IT server racks

Data Center Architecture: From POI to IT Racks

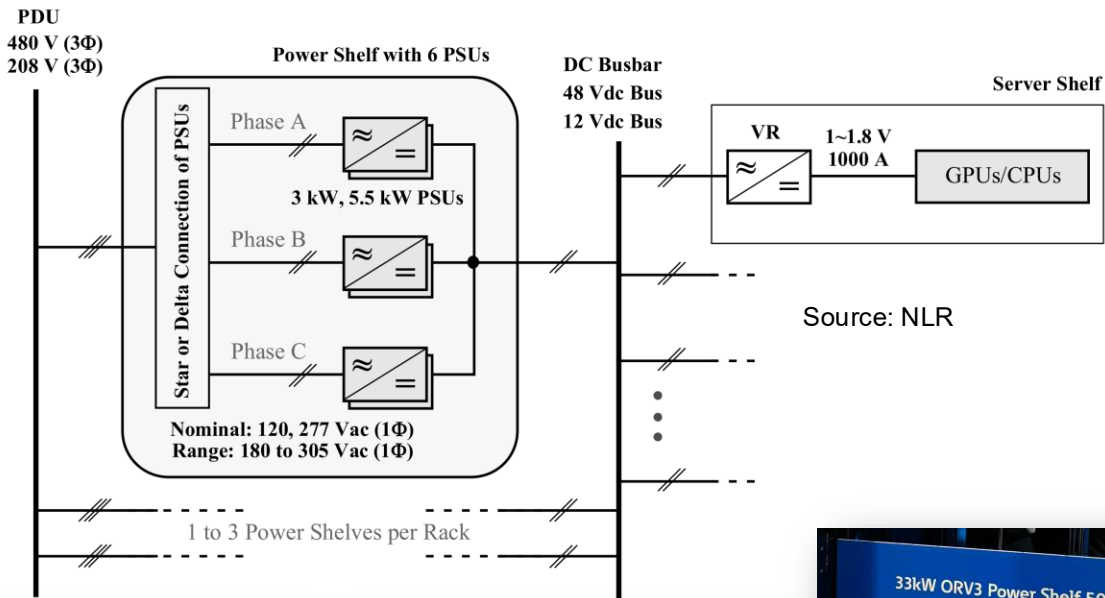


- HV Tx: High-voltage Transformer
- MV Tx: Medium-voltage Transformer
- MSB: Main Switch Board

40x3 MVA Genset in a 100 MW Datacenter

- UPS: Uninterruptible Power Supply
- PDU: Power distribution Unit
- PDU Tx is not always required

Data Center Architecture: Inside IT Racks



Approx. 300 kW



Photos by S. Shah (NLR)



3.6 kW
PSU



5.5 kW
PSU



Two 33 kW Power shelves
each with 6 PSUs (2 x 6 x
5.5 kW)

Factors to Consider for EMT Modeling of Data Centers

Architecture of Data Center Power System

Model Applications

Power Delivery
(from POI to IT Racks)

IT Racks
(from Rack to GPUs/CPUs)

Load
Profile

Transient
Behavior

Small-Signal
Stability

AC UPS

DC UPS

SST

Side Car

Rack Busbar Voltage

PSU

BBU

CBU

Torsional
Modes,
Flicker

Loss of Load,
LVRT

Low
Frequency

High
Frequency

UPS: Uninterruptible Power Supply
PSU: Power Supply Unit
BBU: Battery Backup Unit
CBU: Capacitor Bank Unit
SST: Solid-State Transformer

48 Vdc

800 Vdc

±400 Vdc

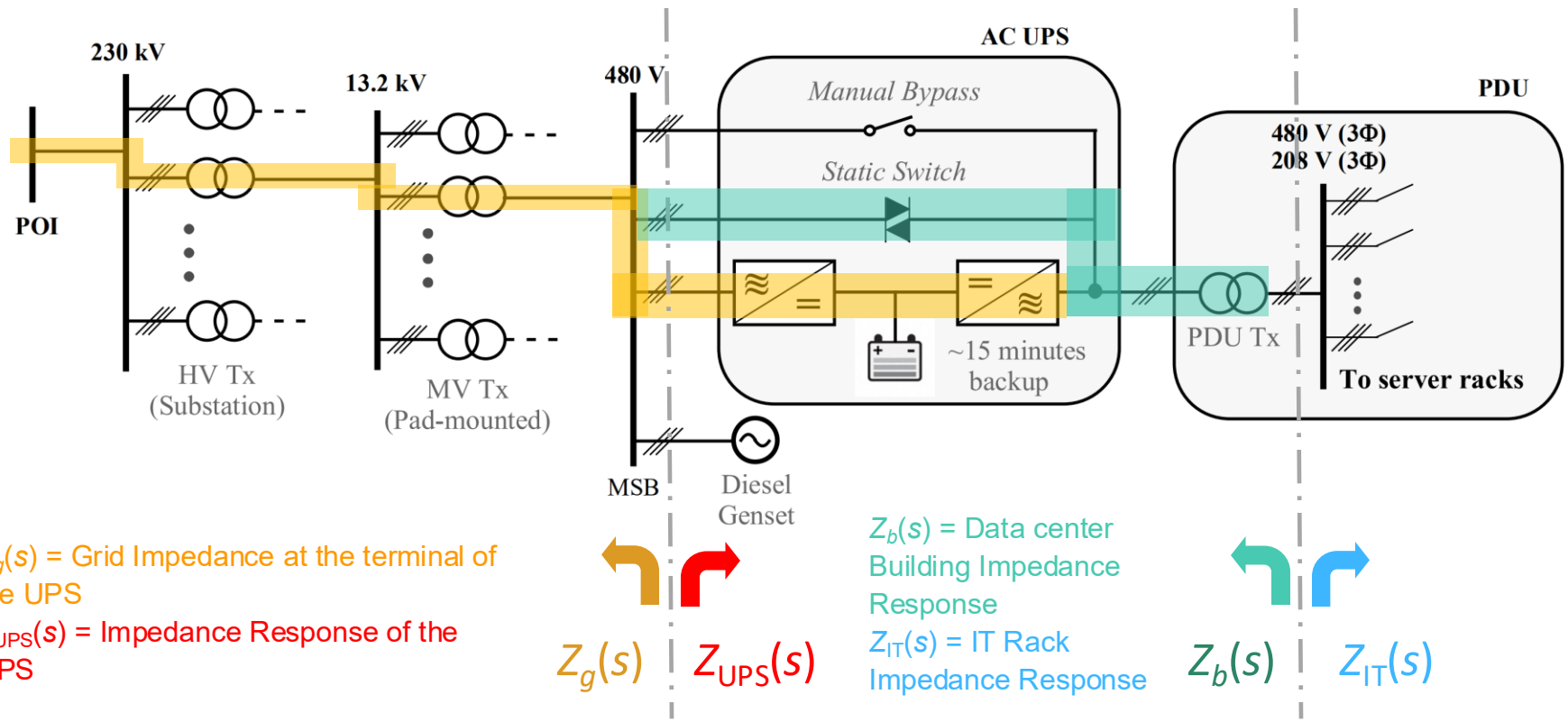
Single-phase
PFC
(single-boost,
double-boost,
bridgeless)

Various impedances in the data center building distribution network and aggregation of power converters play an important role in the model development.

Summary

- Generally, two types of power electronic converters in the data center power systems can interface with the grid:
 - AC UPS
 - PSU
- Tens to hundreds of AC UPS, each rated at few megawatts, are present in a large data center
 - Power electronic converters inside AC UPS can interact with the grid when the AC UPS is operated in so-called **double conversion mode**
- Tens to hundreds of thousands of PSUs, each rated at few kilowatts, are present in a large data center
 - Power electronic converters inside PSU can interact with the grid when the AC UPS is operated in so-called **bypass or eco mode**

Two Types of Converter-Driven Control Interactions



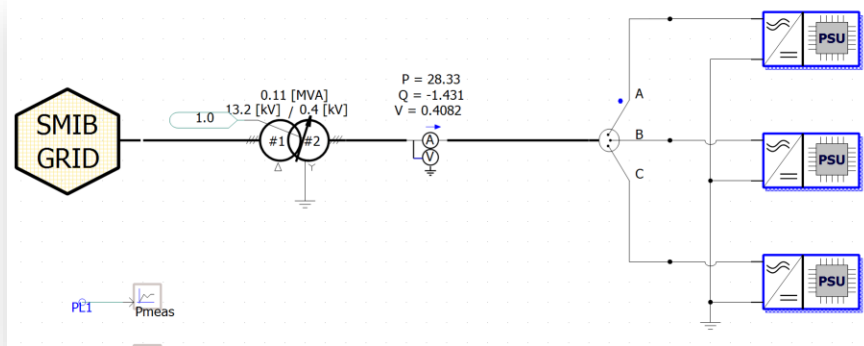
$Z_g(s)$ = Grid Impedance at the terminal of the UPS
 $Z_{UPS}(s)$ = Impedance Response of the UPS

$Z_g(s)$ $Z_{UPS}(s)$

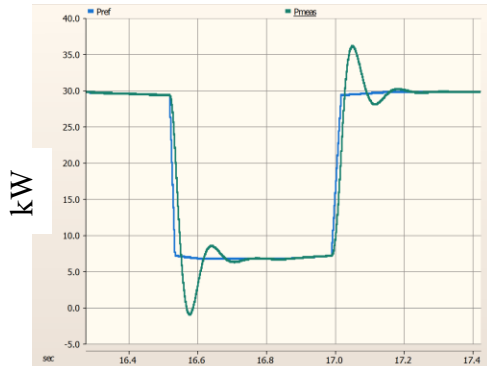
$Z_b(s)$ = Data center Building Impedance Response
 $Z_{IT}(s)$ = IT Rack Impedance Response

$Z_b(s)$ $Z_{IT}(s)$

PSCAD Model of a 33 kW IT Rack (3 x 2 x 5.5 kW PSUs)

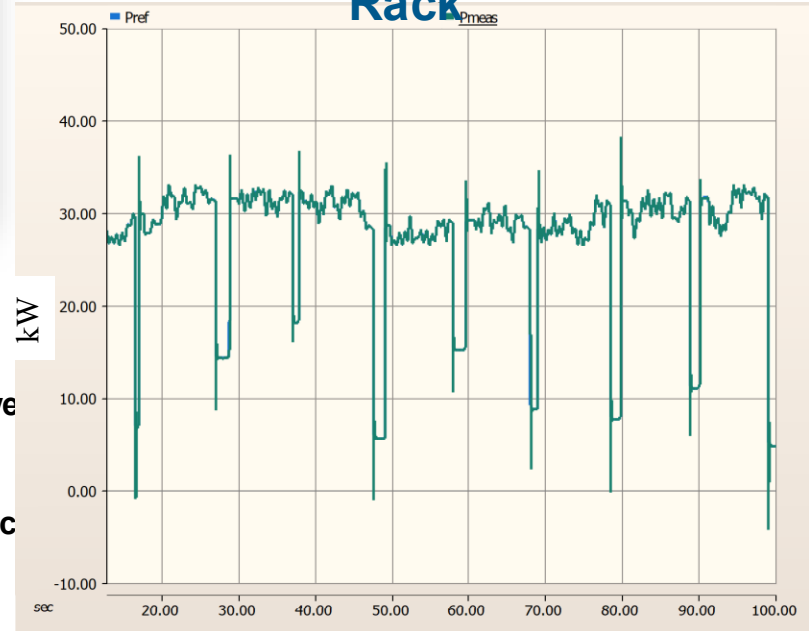


AC vs DC Power



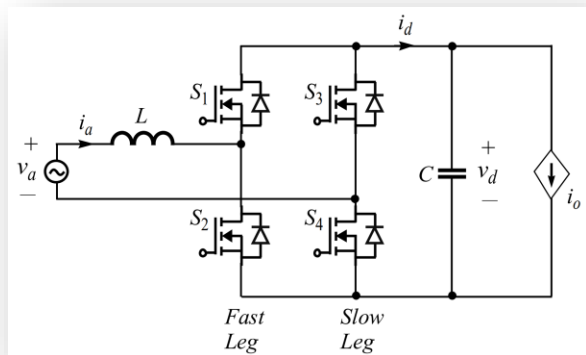
- **P_{ref}**: DC Power (GPU Power Consumption)
 - Ramp rate = 43 pu/sec
- **P_{meas}**: AC Power by IT Rack (Experienced by UPS)
 - Ramp Rate = 22 pu/sec
 - Overshoot: 0.25 p.u.

Power Consumption by the IT Rack

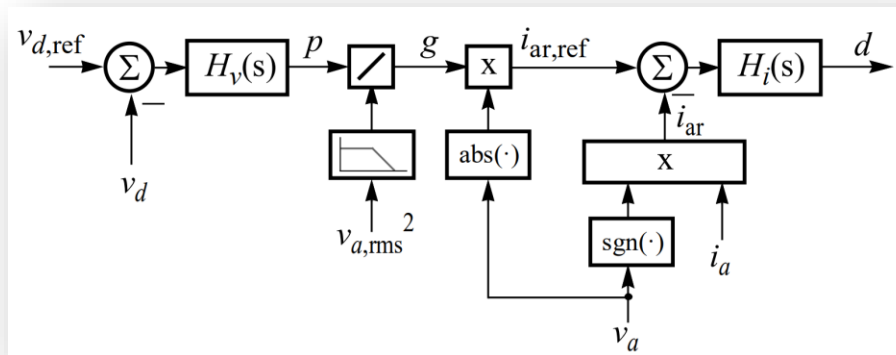


Single-Phase Bridgeless Totem-pole PFC (TPPFC)

• Topology



• Control Design

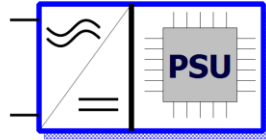


- Fast leg switching frequency is 50 kHz to 150 kHz
 - **Simulation timestep should be smaller than 1 μ s to capture the switching dynamics**
 - Not important for power system studies
- Slow leg switching frequency is the same as the fundamental frequency, 60 Hz
- Current control bandwidth is 5 kHz to 15 kHz
 - **Simulation timestep should be smaller than 10 μ s to capture the current control dynamics**
 - Usually not important for power system studies

PSCAD Model of a Single-Phase TPPFC-Based PSU

• PSCAD Library Component

Input 1 ϕ
Voltage:
LVAC



Output
Voltage: 400
Vdc

• Features of the Model

- Can represent PSUs of different ratings
- Advanced averaging techniques to enable fast EMT simulations
 - Three modes of operation for the model
- GPU load can be represented as constant resistance, constant current, or constant power load
- GPU load profile can be supplied directly to the EMT model

Generic Electromagnetic Transient (EMT) Model of a Power Supply Unit (PSU) Based on Single-Phase Totem-Pole Power Factor Correction (TPPFC) Converter Topology
National Laboratory of the Rockies (NLR), Golden, CO, 80401
Authors: Shahil Shah and Weihang Yan (For any queries, please contact at shahil.shah@nlr.gov)

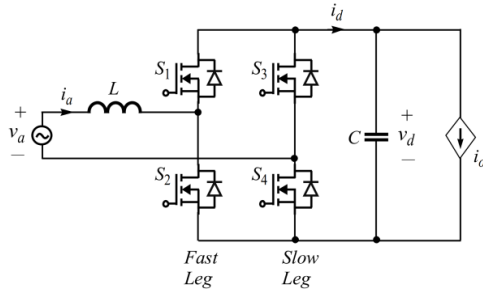
Operation Modes:
This model has three operation modes. Either of the three modes can be used by properly selecting the configuration for three layers used in the simulation mode.

1. Switching Mode: This mode enables simulation of switching model with semiconductor switches represented by GSN FETs. Switching frequency is set to 50 kHz. Maximum recommended simulation timestep for this mode is 0.1 μ s
 - o "Switched" layer: Enabled; "Averaged" layer: Disabled; "CurrentControl" layer: Actual
2. Svt-Averaged Mode: This mode uses averaged model that removes switching dynamics. This mode accurately represents the dynamics of the PSU upto half of the switching frequency. Maximum recommended simulation timestep for this mode is 10 μ s.
 - o "Switched" layer: Disabled; "Averaged" layer: Enabled; "CurrentControl" layer: Actual
3. Double-Averaged Mode: This mode removes switching dynamics as well as the dynamics of the current control loop. This mode accurately represents the dynamics of the PSU up to around 300 to 500 Hz. Maximum recommended simulation timestep for this mode is 500 μ s.
 - o "Switched" layer: Disabled; "Averaged" layer: Disabled; "CurrentControl" layer: Ideal

Averaging Techniques

- Switching Averaged Model

- $T_s < 10 \mu s$



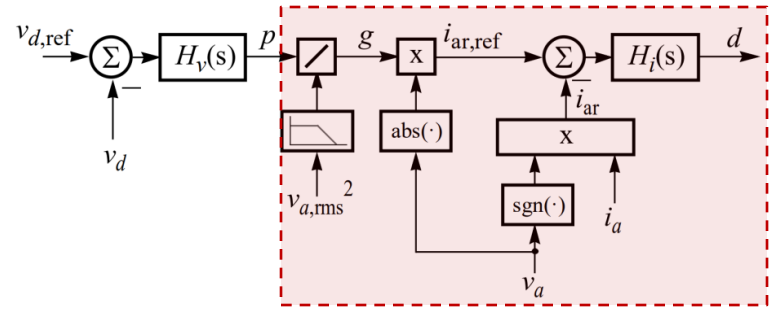
$$\text{for } v_a \geq 0: \begin{cases} L \frac{di_a}{dt} = v_a - (1-d)v_d \\ i_d = (1-d)i_a \end{cases}$$

$$\text{for } v_a < 0: \begin{cases} L \frac{di_a}{dt} = v_a + (1-d)v_d \\ i_d = -(1-d)i_a \end{cases}$$

- Captures dynamics up to 10kHz

- Double Averaged Model

- $T_s < 100 \mu s$



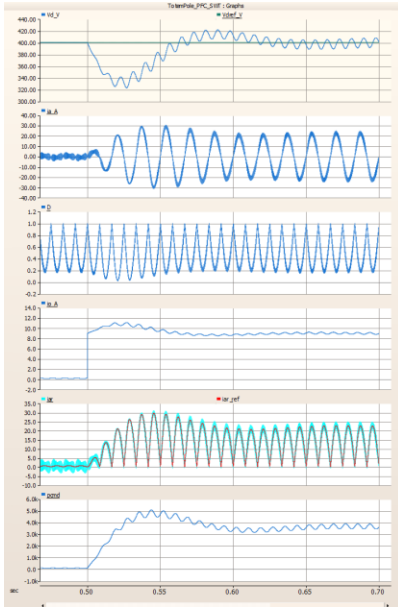
$$i_{ar} = i_{ar,ref} \Rightarrow i_a = p \cdot \frac{v_a}{V_{rms}^2} \text{ and } i_d = p \cdot \frac{v_a^2}{V_{rms}^2} \cdot \frac{1}{v_d}$$

- Captures dynamics up to 1 kHz

Comparison of 5.5 kW TPPFC Models

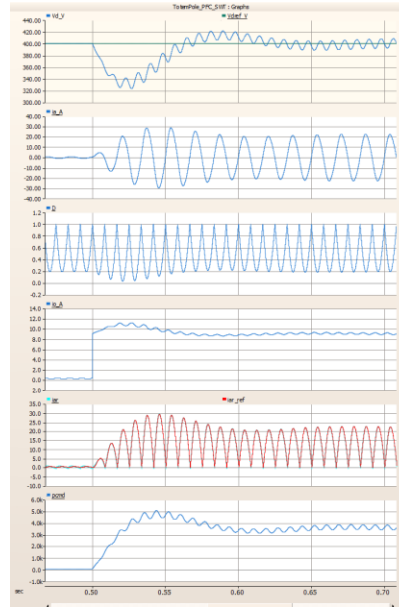
V_d
 i_a
 d
 i_o
 i_{ar}
 p

Switched Model



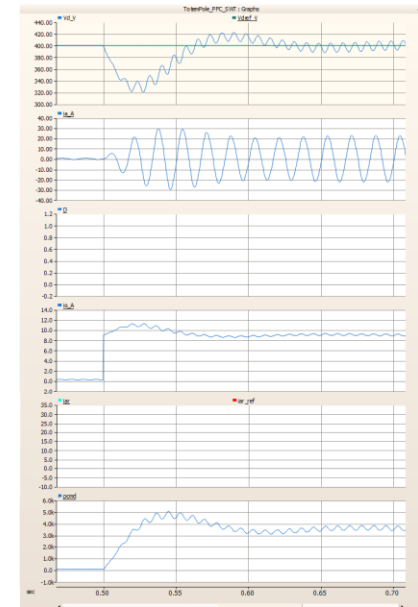
- Simulation time step: 0.1 μ s
- Time for simulating one sec.: 53 s

Swt-Averaged Model



- Simulation time step: 10 μ s
- Time for simulating one sec.: 0.86 s

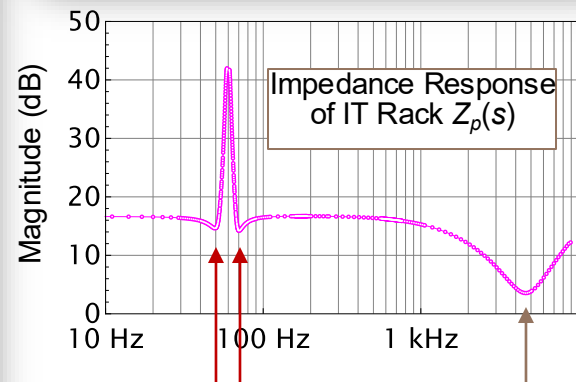
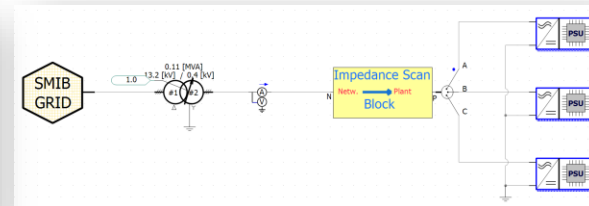
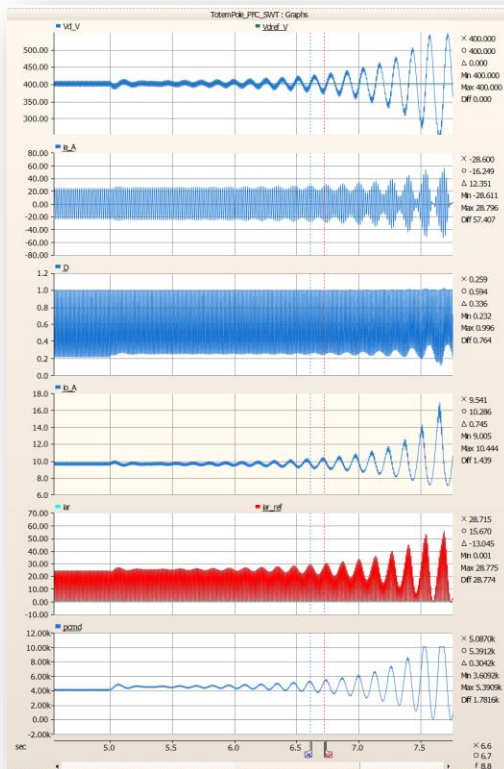
Double-Averaged Model



- Simulation time step: 500 μ s
- Time for simulating one sec.: 0.12 s

Weak Grid Instability in Datacenters

- UPS Bypass Mode
 - Instability observed at 9 Hz under weak grid conditions
 - The frequency of instability is strongly correlated with dc voltage control design in PSUs used within IT Racks
- Double Conversion Mode
 - Weak grid instability mechanism is the same as in IBRs



**Dips from dc
voltage control**

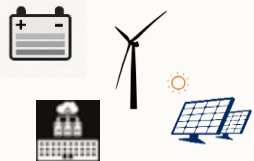
BW: 10 Hz

**Dips from
current control**

BW: 5 kHz

Impedance-Based Stability Analysis

IBR/LEL



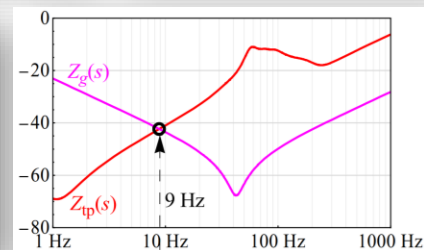
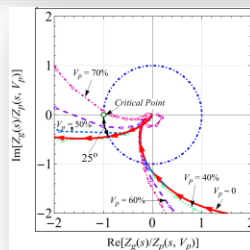
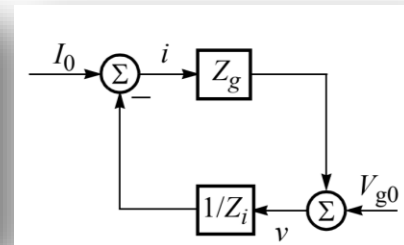
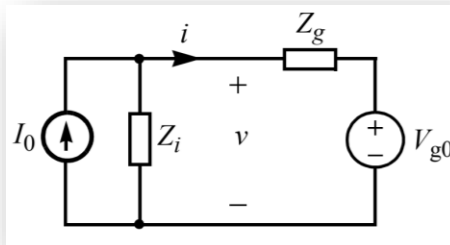
$Z_i(s)$

$Z_g(s)$



GRID

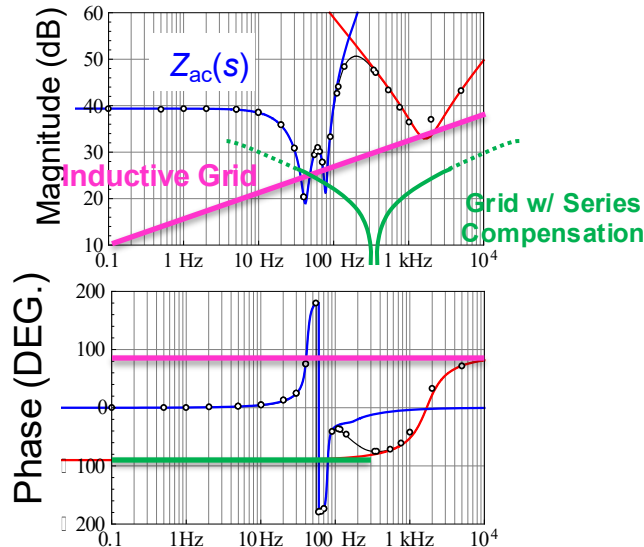
- **Loop Gain:** $Z_g(s)/Z_i(s)$
- **Pre-requisite:**
 - *Standard Criterion:* IBR and the Grid are Separately Stable
 - *Reversed Criterion:* IBR and the Grid are Stable when Interconnected



Mechanism of Control Interactions in Data Centers

• Impedance of Single-Phase VSC

$$Z_{ac}(s) \approx \left\{ \frac{1}{sL + V_{dc}H_i(s)} - \frac{j}{2}I_1[T_p(s - j\omega_1) - T_n(s + j\omega_1)] \right\}^{-1}$$



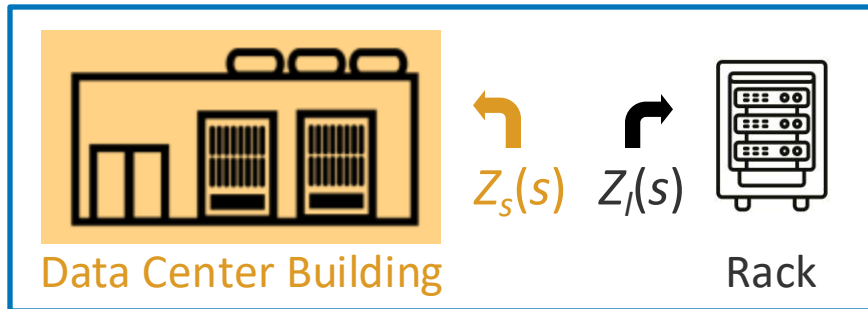
• Impedance response of single-phase VSCs (such as PSUs) has **two dips** around the fundamental frequency and it exhibits negative damping

- These dips can interact adversely with inductive or capacitive impedance of the source (grid + distribution network) and potentially create low-frequency oscillations
- The distance of the dips from the fundamental frequency is correlated with the bandwidth of dc-bus voltage control in the single-phase PFC front-end of the PSU.

Impedance-Based Specifications from Meta

- Building Impedance Ratio (BIR) is the ratio of PSU base impedance (V^2/P) to building impedance ($2\pi f_1 L_s$)
 - It is equivalent to grid Short-Circuit Ratio

$$BIR = \frac{V^2}{P} \cdot \frac{1}{2\pi f_1 L_s}$$



- Building Requirement: Must be designed to have high BIR**

| BIR at Rack Terminal | Conclusion |
|----------------------|---------------|
| > 2.5 | Pass |
| 2.0 to 2.5 | Marginal Pass |
| 1.5 to 2.0 | Marginal Fail |
| < 1.5 | Fail |

- PSU Requirement: Must be stable with low BIR**

| Min. BIR Req'd. for Stability | Conclusion |
|-------------------------------|---------------|
| > 2.0 | Fail |
| 1.5 to 2.0 | Marginal Fail |
| 1.0 to 1.5 | Marginal Pass |
| < 1.0 | Pass |

Reference: Melaku Mihret, OCP Summit 2020

Summary

- AC UPS are the power electronic converters seen by the grid withing a data center when they operate in the double conversion mode
 - Modeling of AC UPS is very similar to IBRs, if not the same, as they use similar inverters (PCS). Hence, existing knowhow on EMT modeling of IBRs can be directly leveraged.
- PSUs are the power electronic converters seen by the grid within a data center power system during normal operation when AC UPS is operated in the bypass mode.
 - Single-phase PFC ac-dc converters are the front-end within a PSU and they must be accurately modeled for evaluating control interactions between datacenters and power grids.
 - The switching frequency of PSUs range from 10s to 100s of kHz. The current control bandwidths range from few to 10s of kHz. These high frequency dynamics do not penetrate the grid; hence, switching frequency and current control dynamics can be ignored in the PSU models used for grid reliability studies.

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