ELECTRIC POWER ENGINEERS

ENERGY ENGINEERING EXPERTS

GENERATION | TRANSMISSION | DISTRIBUTION

BEYOND INERTIA FEATURE FOR GRID FORMING INVERTERS AND CONVERTER-BASED DOMINATED LOADS FOR GRID OF FUTURE

SAM MALEKI

POWER SYSTEM TODAY

Generation units

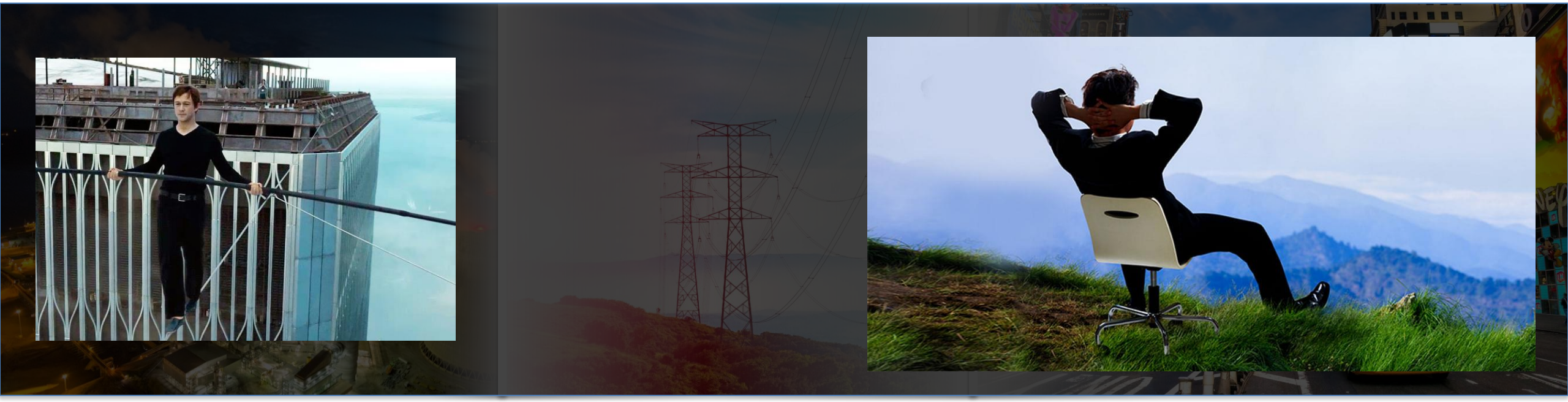
Transmission lines

Loads

NETWORK STABILITY (LOAD AND GENERATION)

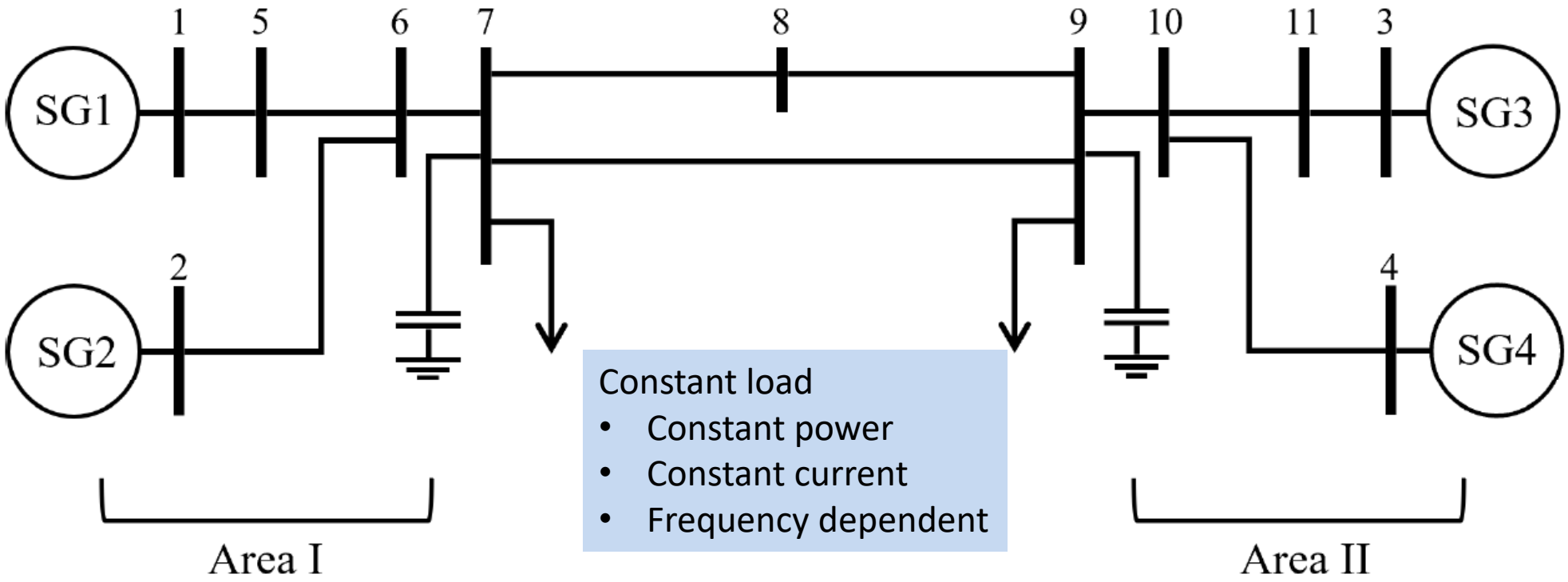
Generation units

Loads



NETWORK STABILITY (LOAD AND GENERATION)

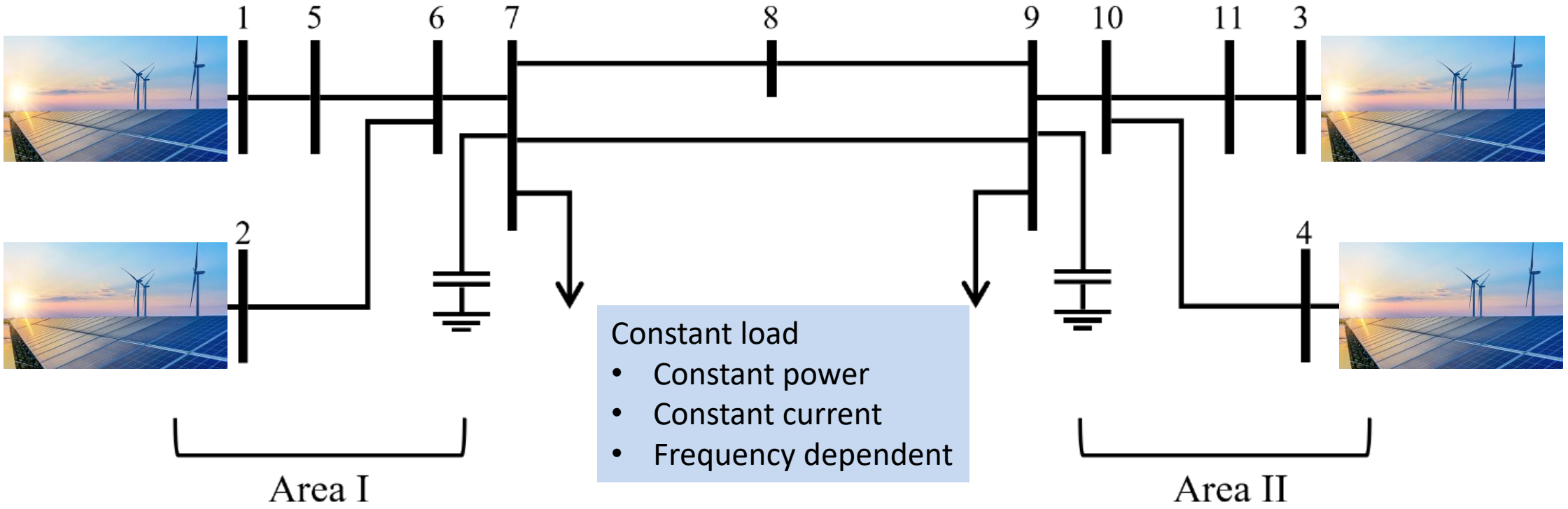
Power System stabilizers



Constant load
- Constant power
- Constant current
- Frequency dependent

NETWORK STABILITY (FUTURE POWER SYSTEMS)

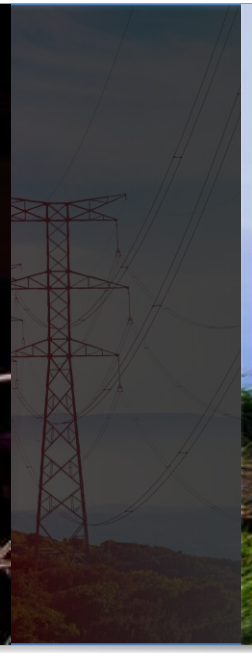
No Power System stabilizers!



Constant load
- Constant power
- Constant current
- Frequency dependent

CHALLENGES FOR FUTURE GRID

Generation units



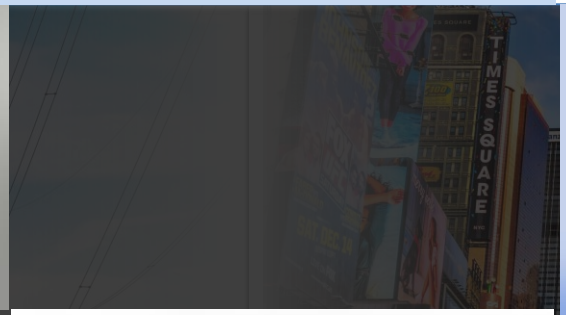
Loads

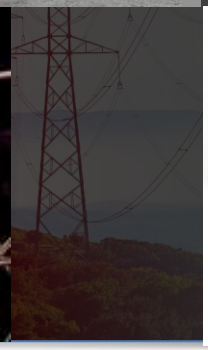
ADDITIONAL STABILIZER MEANS

Generation units

STATCOM, Synchronous Condenser

Loads



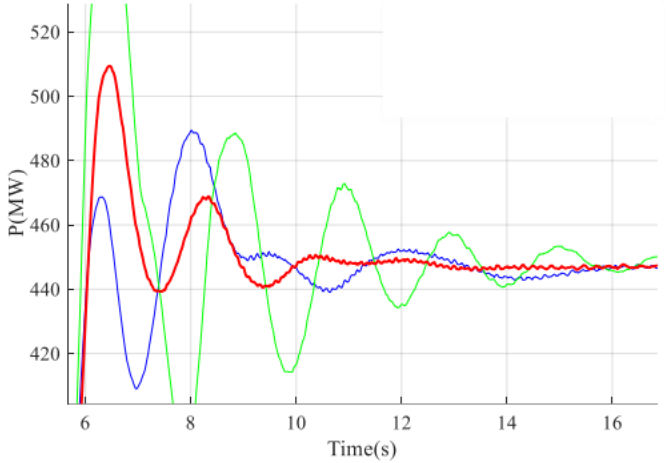


GRID FORMING INVERTER CONTROLS

Grid Forming Inverters

Virtual Synchronous Machines

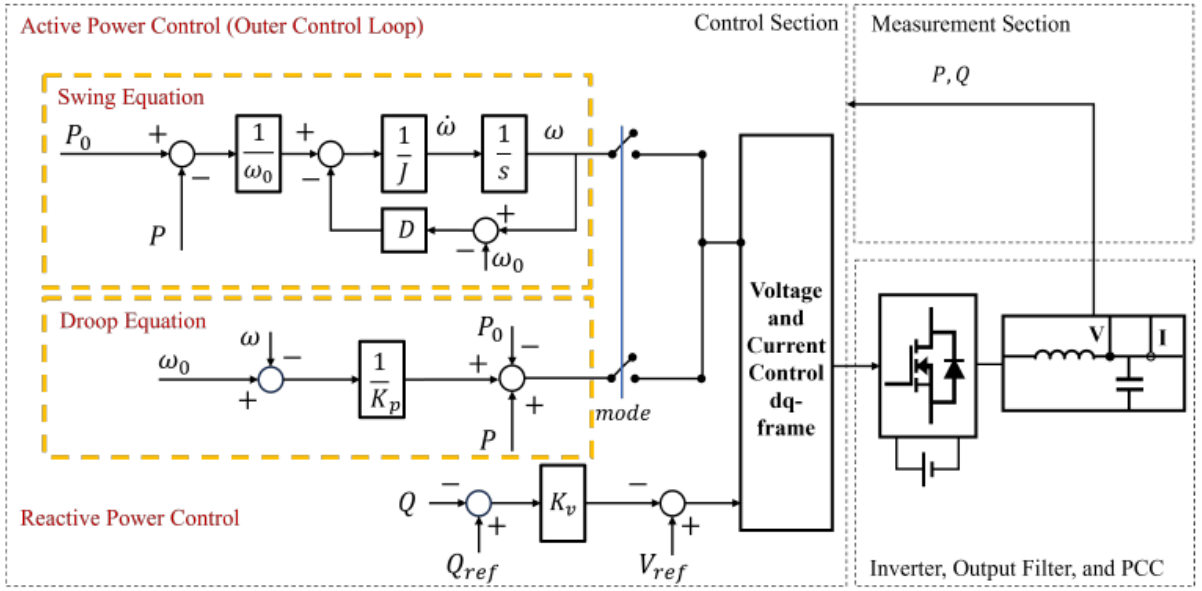
$$\begin{cases} J\omega_0 \frac{d\omega}{dt} + D\omega_0(\omega - \omega_0) = P_0 - P \\ \frac{d\theta}{dt} = \omega \\ P = \frac{V \cdot V_{PCC}}{X} \sin(\delta - \delta_{PCC}) \end{cases}$$

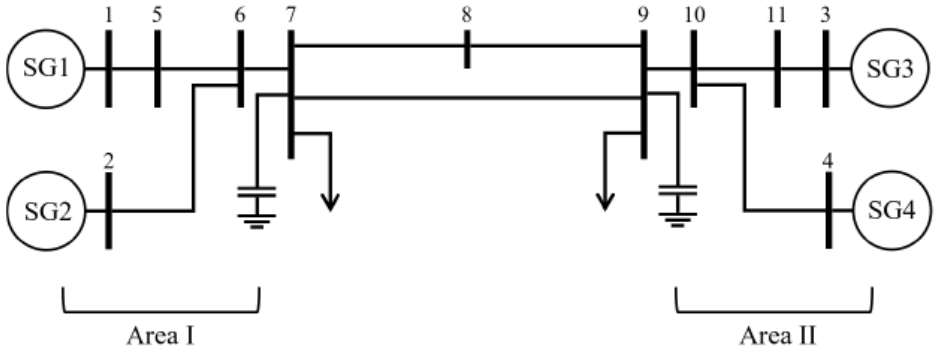


Droop based

$$(\omega - \omega_0) = -k_p(P - P_0)$$

STUDY SYSTEMS IN EMT AND SMALL SIGNAL





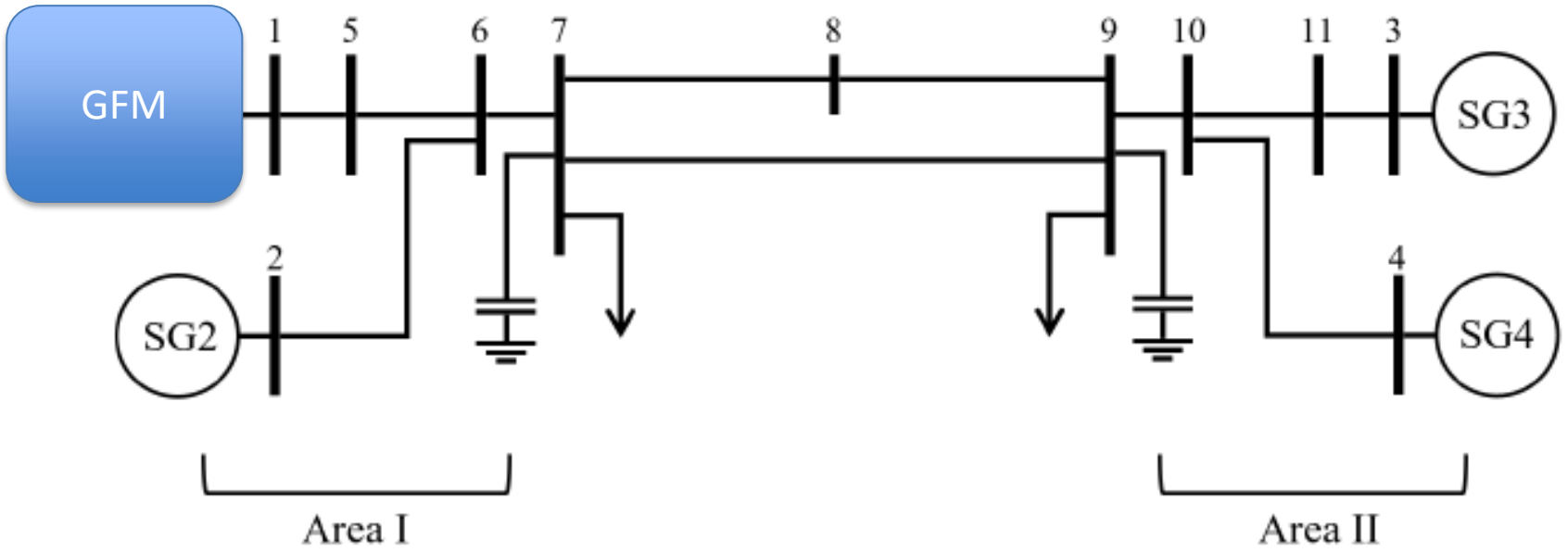
Grid Forming Inverters

- **Small Signal in MATLAB**
- **EMT model in PSCAD**

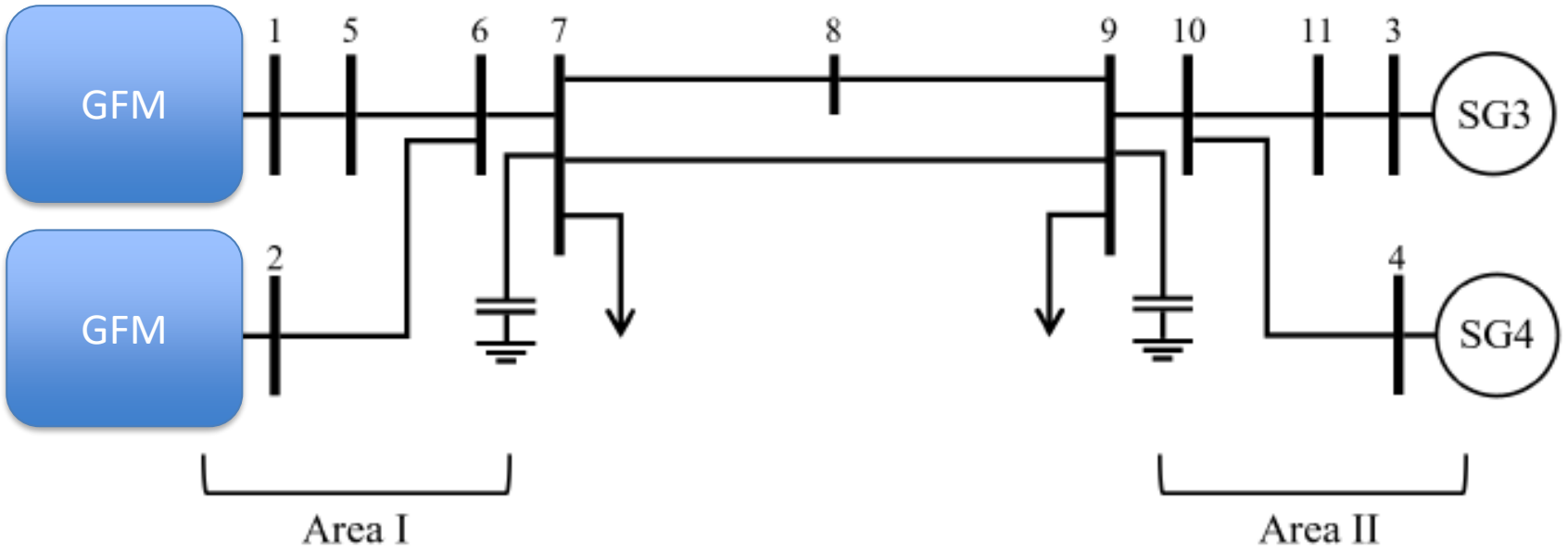
Two Area power system

- **Small signal in MATLAB**
- **EMT model in PSCAD**

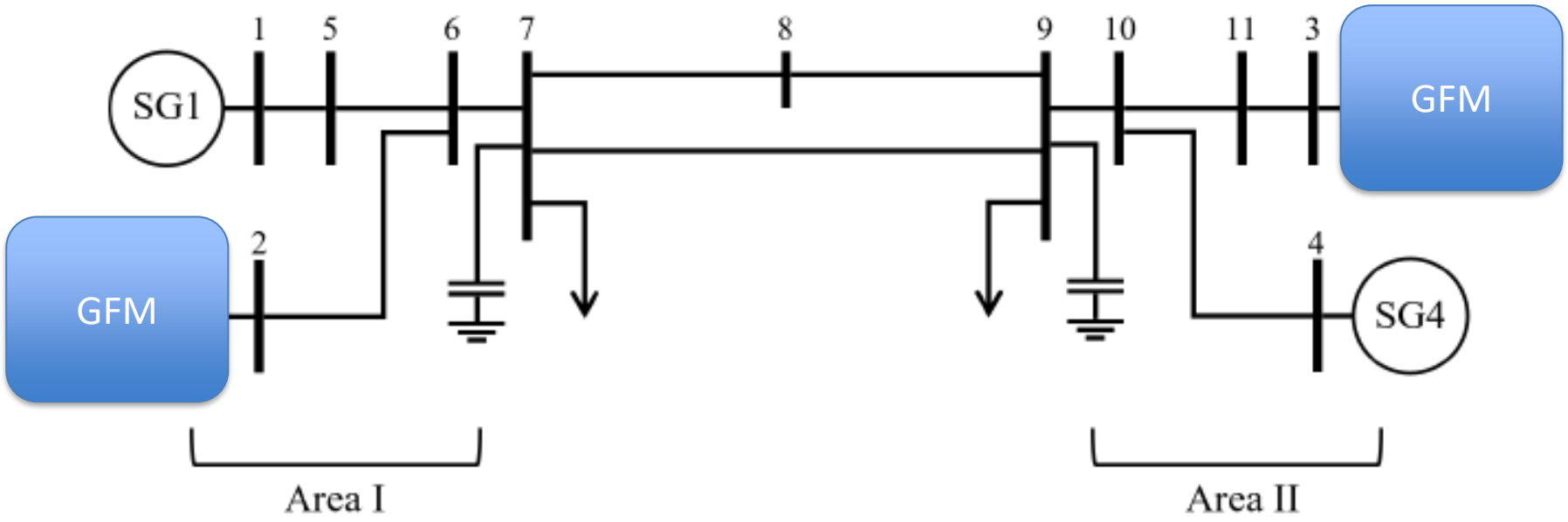
VARIOUS SCENARIOS



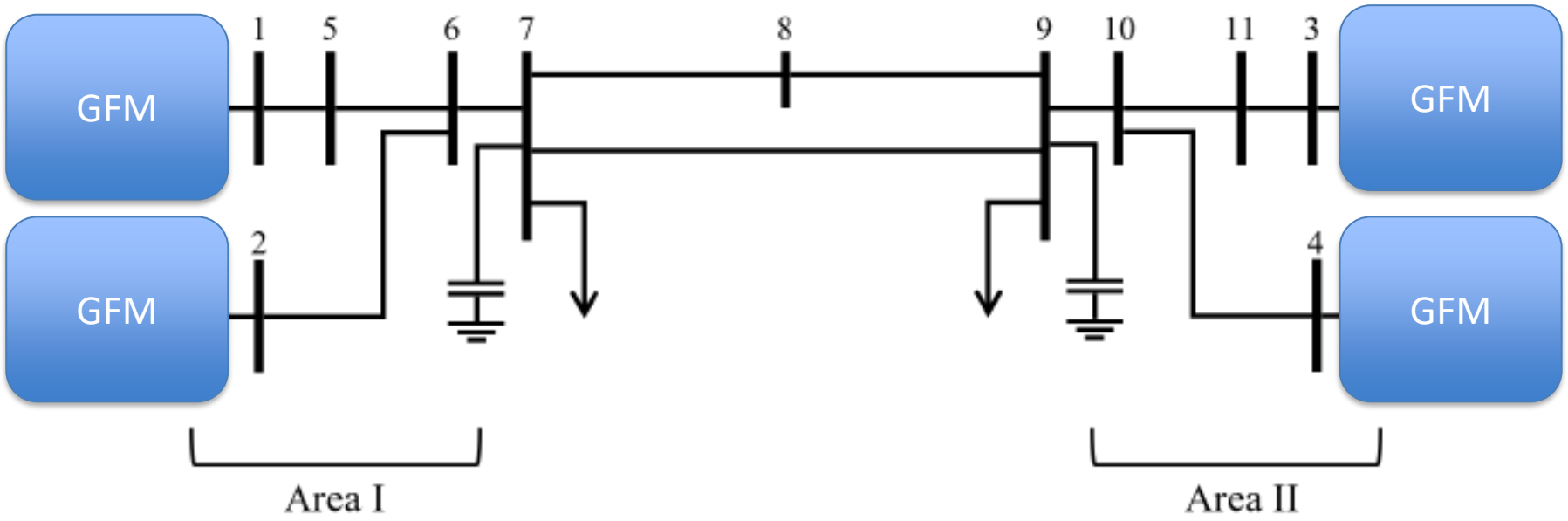
VARIOUS SCENARIOS



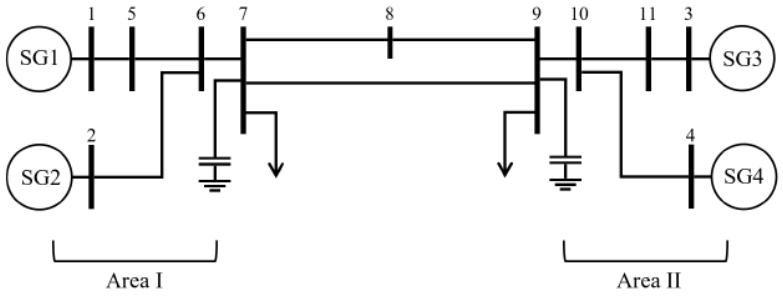
VARIOUS SCENARIOS

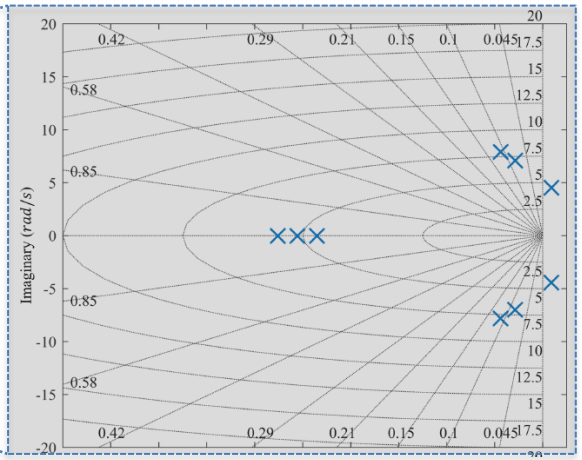


VARIOUS SCENARIOS

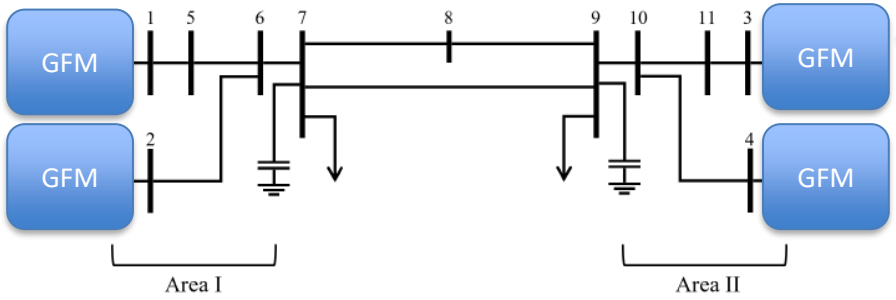


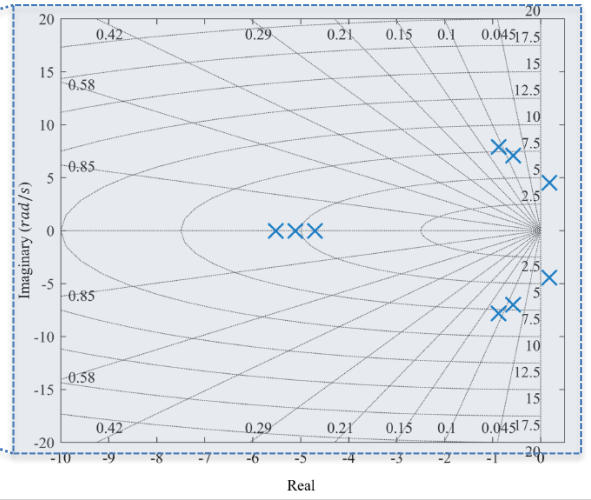
SMALL SIGNAL ANALYSIS- VSM MODE





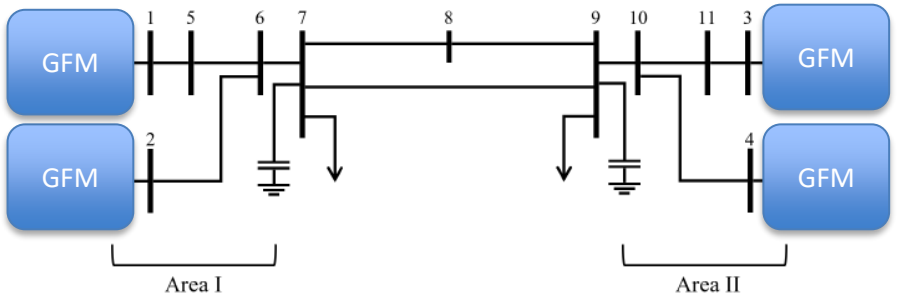
GFM in VSM mode

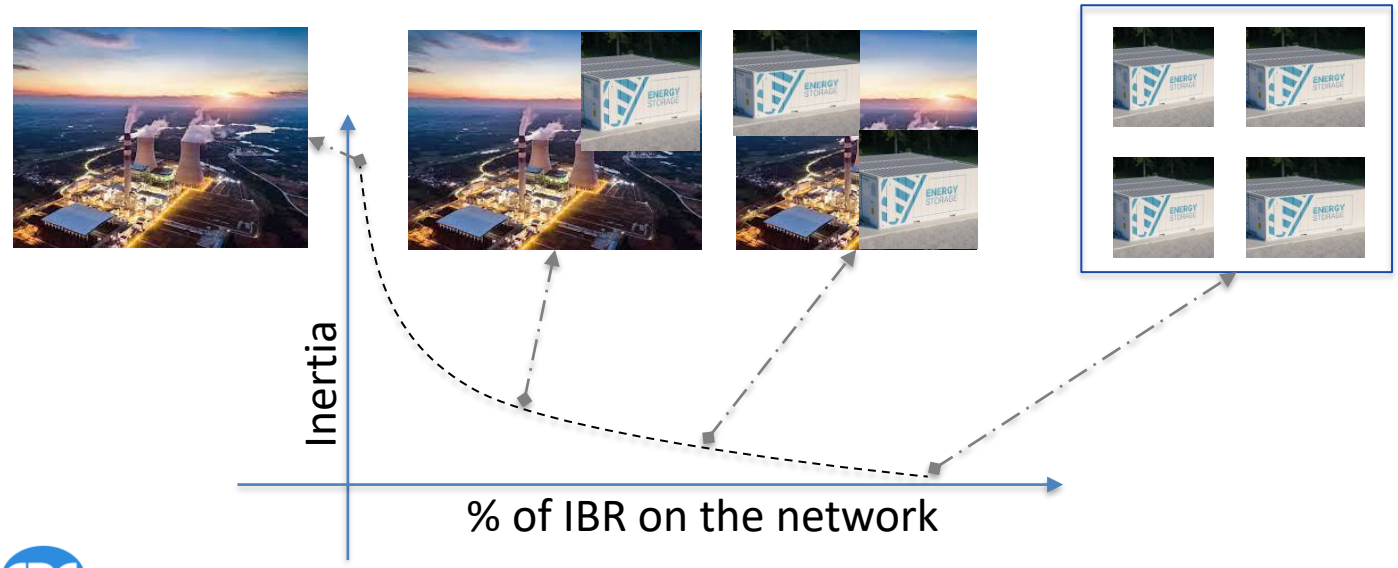


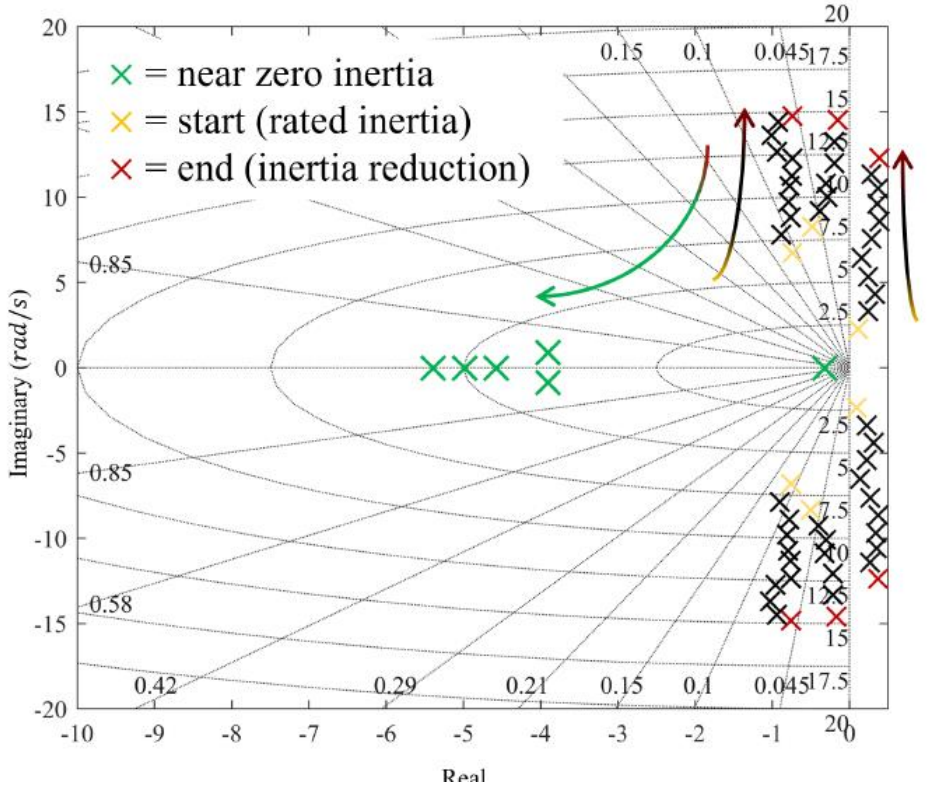


SMALL SIGNAL ANALYSIS- DROOP MODE

GFM in Droop mode

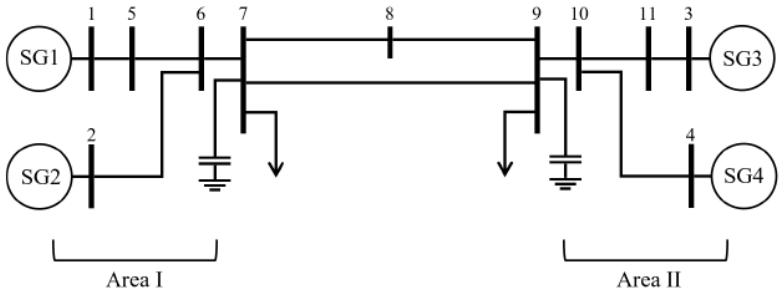


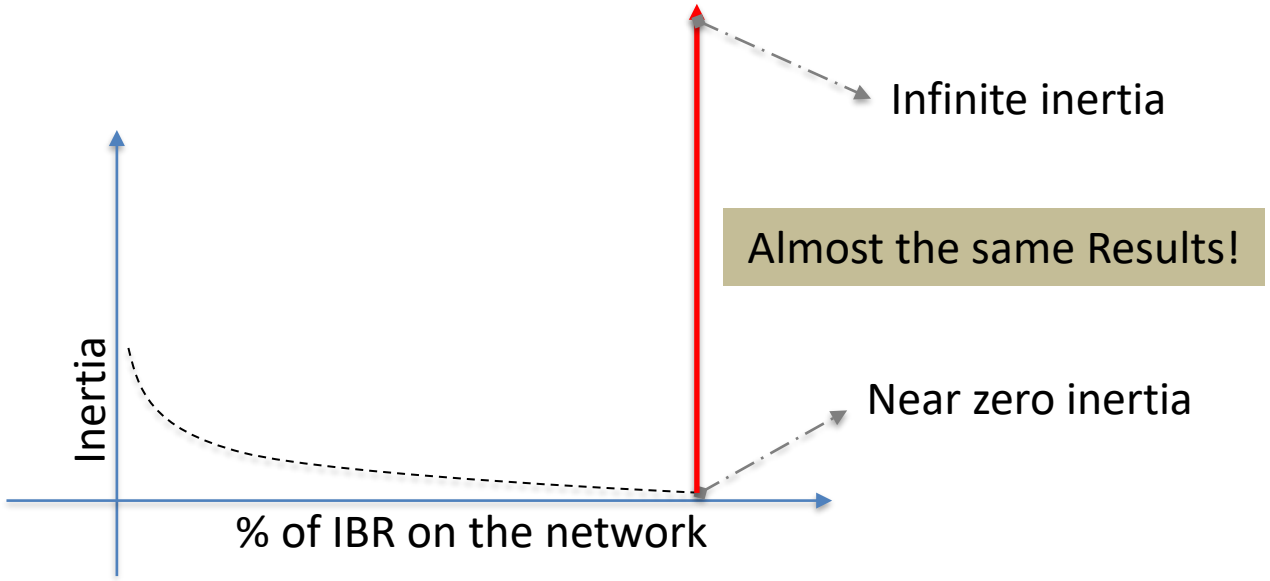




BEYOND INERTIA FEATURE

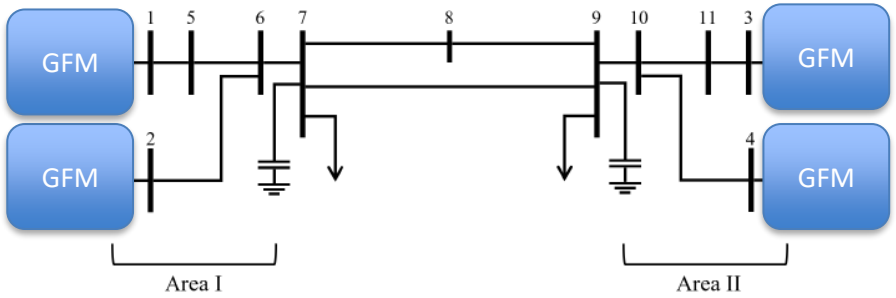
Infinite inertia for the generators 99999

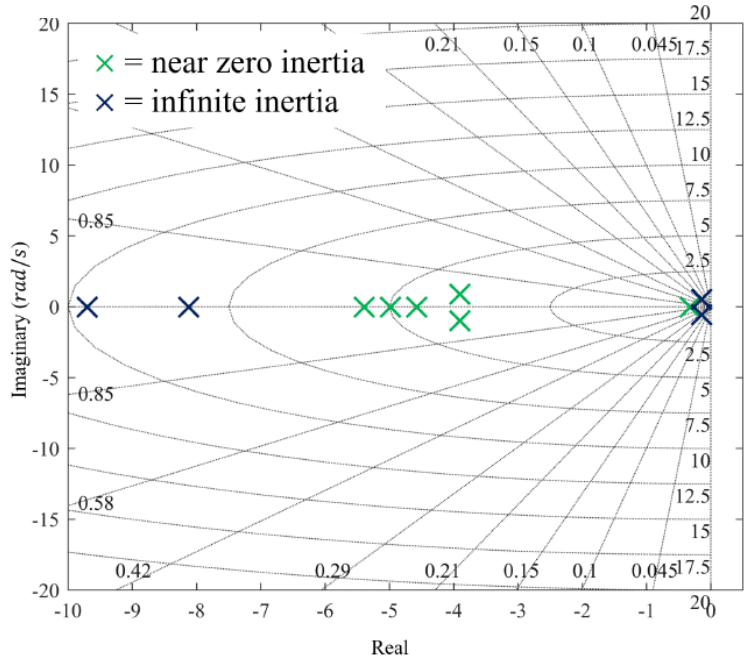




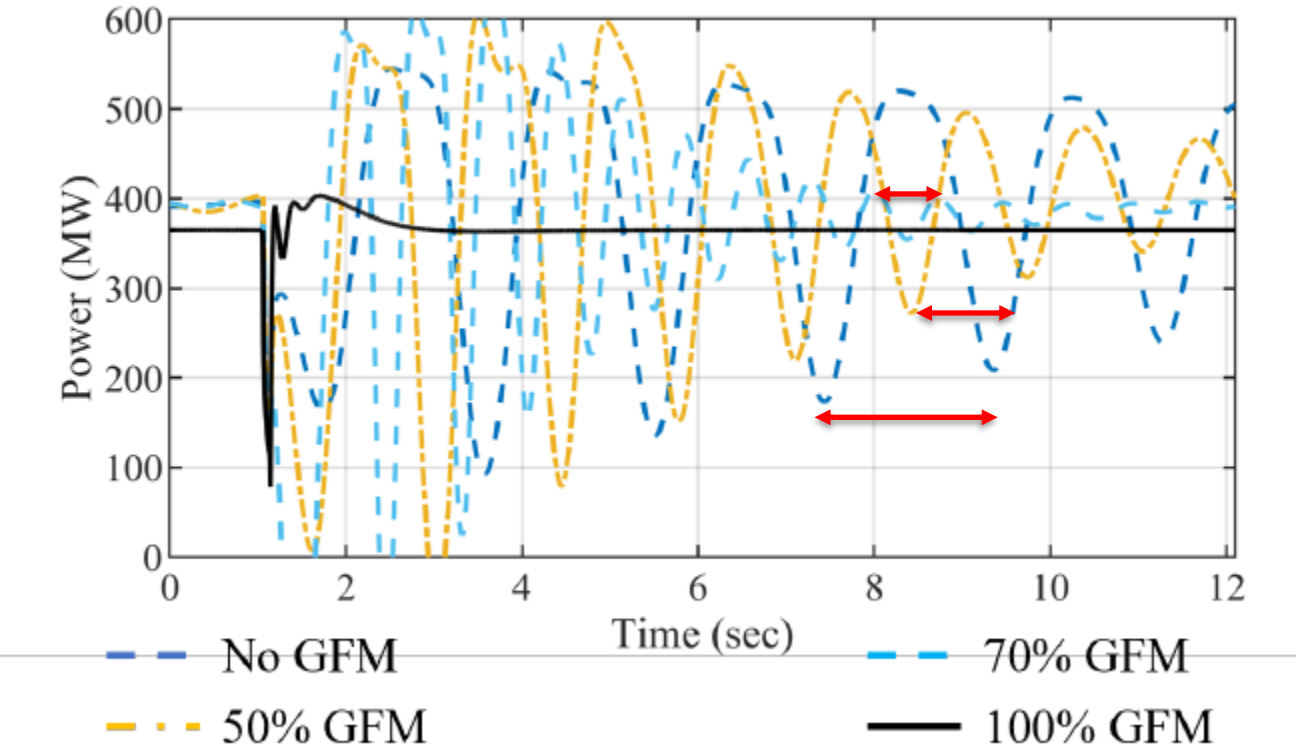
Almost the same Results!

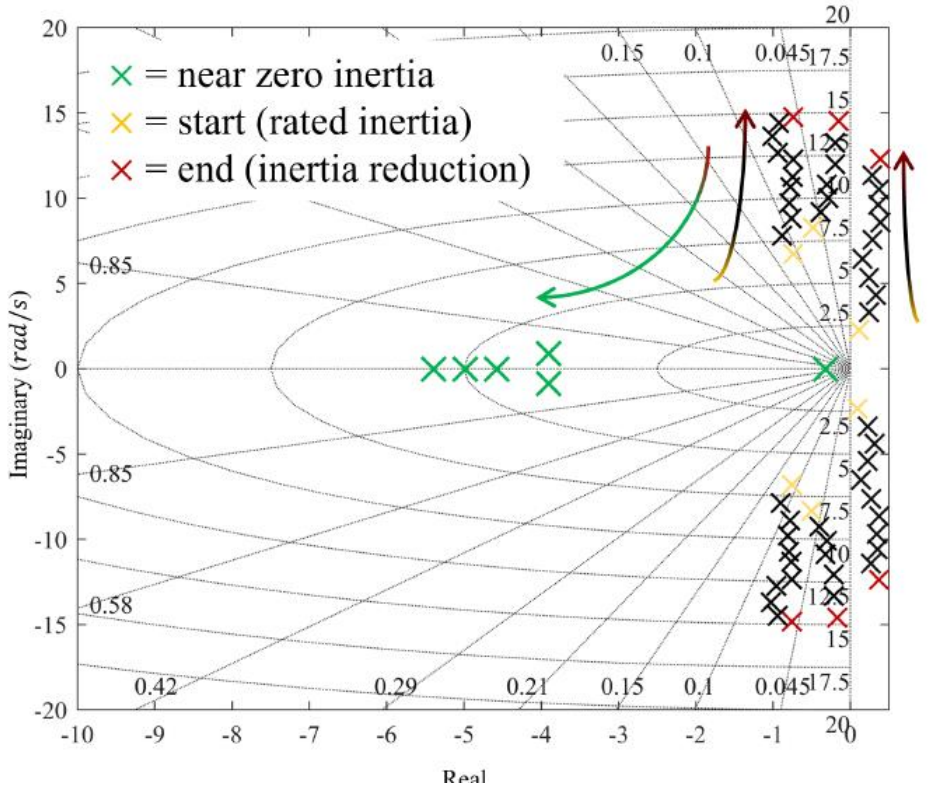
GFM in Droop mode





EMT STUDIES VS SMALL SIGNAL ANALYSIS





Note, for this study we kept all the lines in service to have an initial stable case

LOAD DYNAMIC EFFECT ON SYSTEM STABILITY

Constant load model (*system with high short circuit level*)

Composite load model (*system with low short circuit level*)

Inverter based load model

- System short circuit
- Phase lock loop
- Controller units

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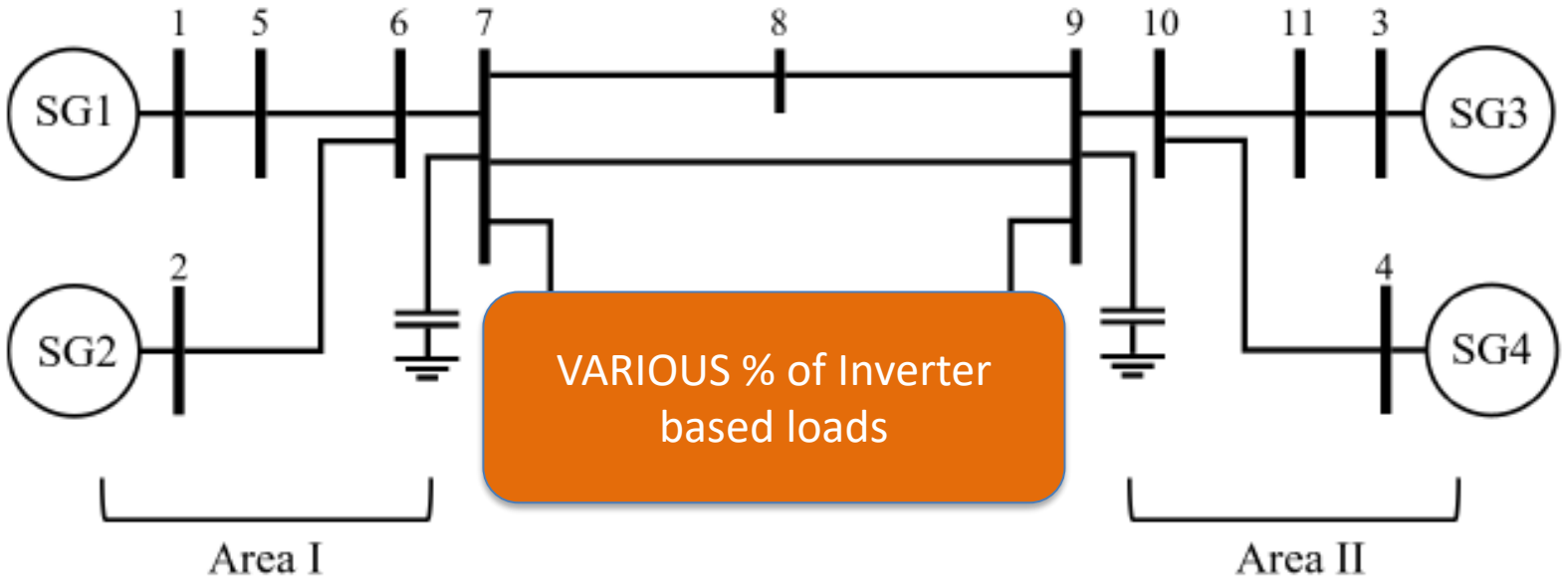
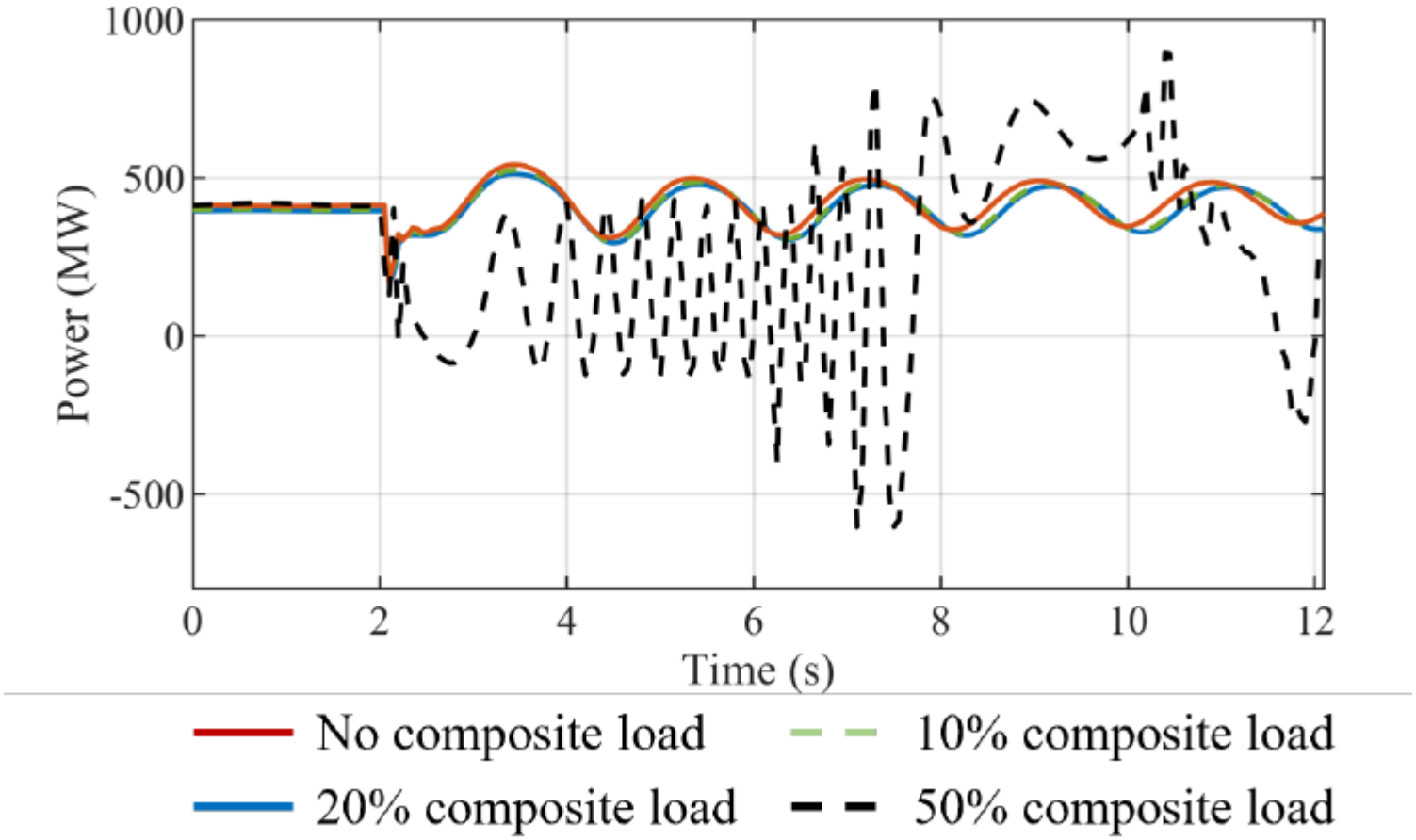
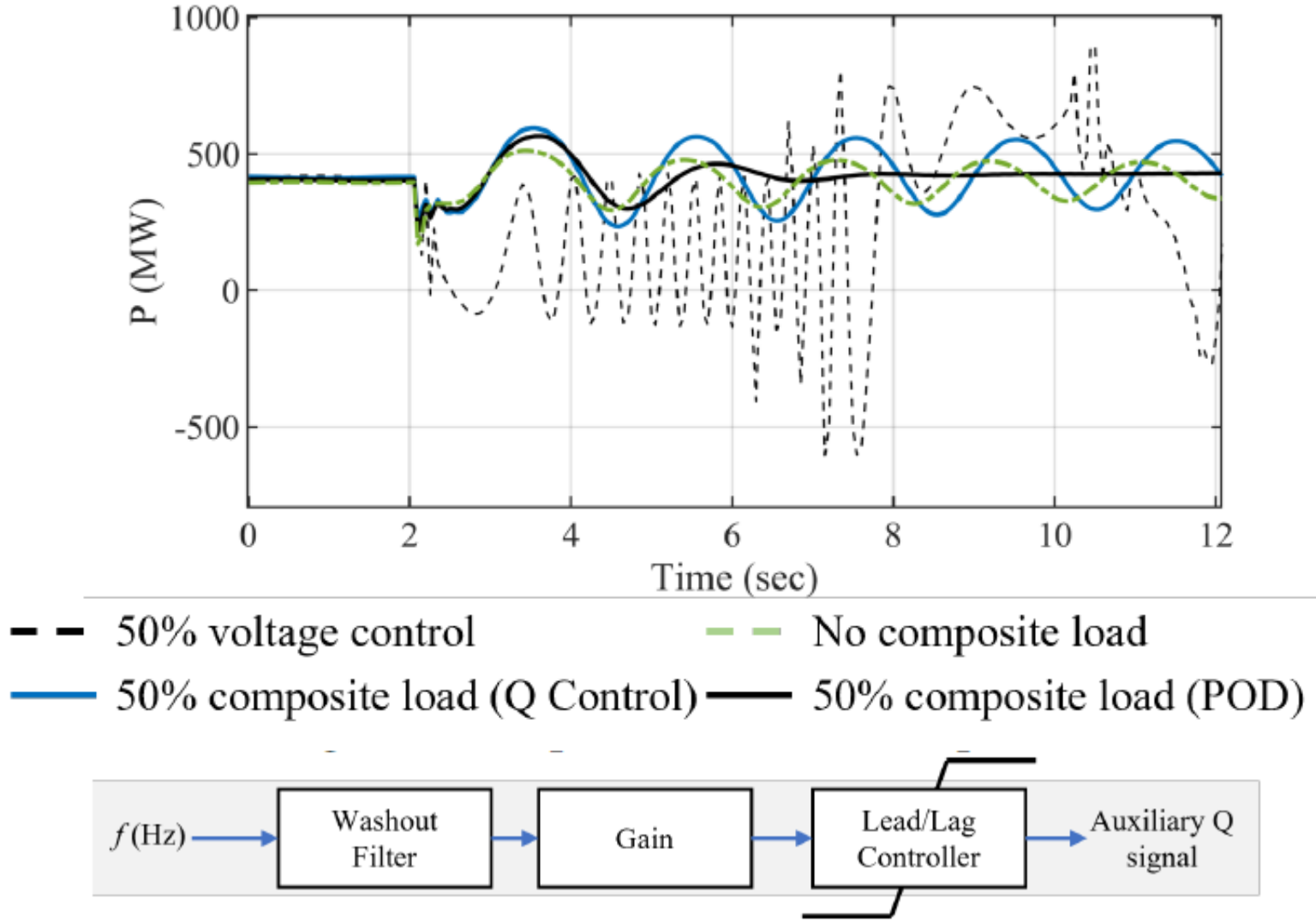
LOAD DYNAMIC EFFECT ON SYSTEM STABILITY



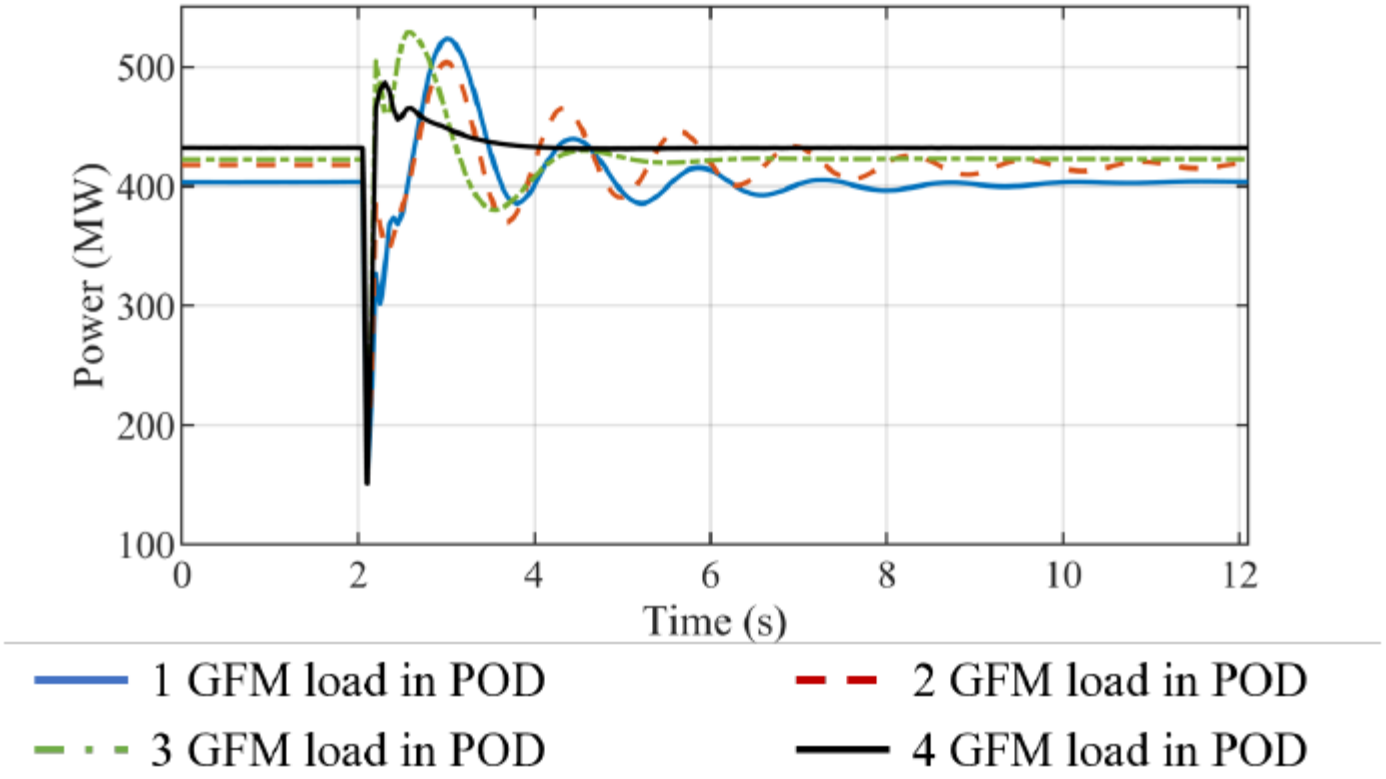
LOAD DYNAMIC EFFECT ON SYSTEM STABILITY

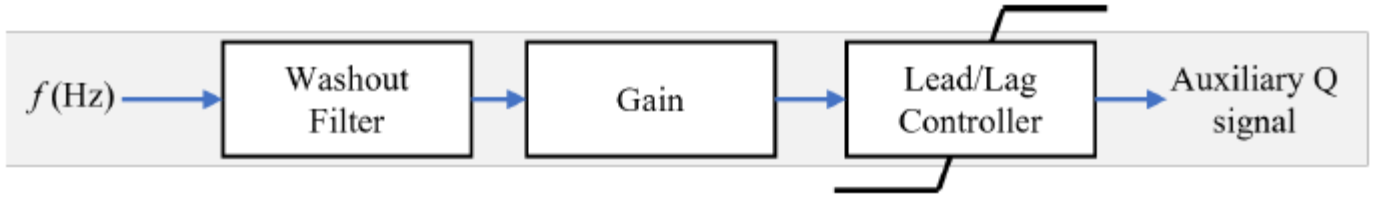


POD CONTROL MODES FOR LOADS



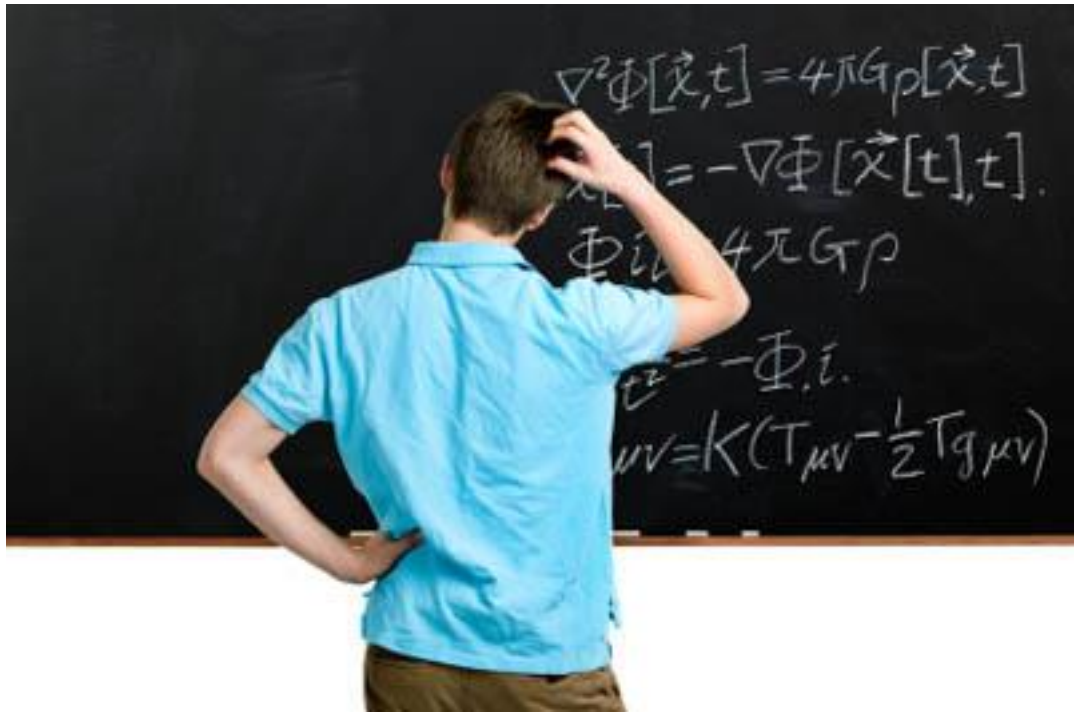
GFM IN DROOP AND LOADS WITH POD





Some more studies!

- Transition period
- Effect of the location of GFM
- VSM or Droop?



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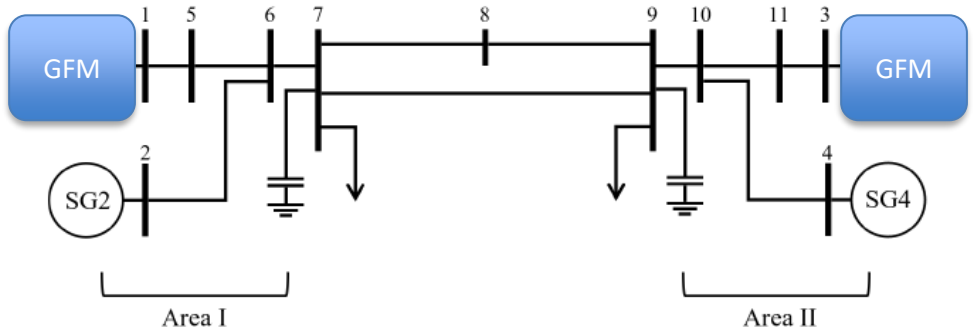
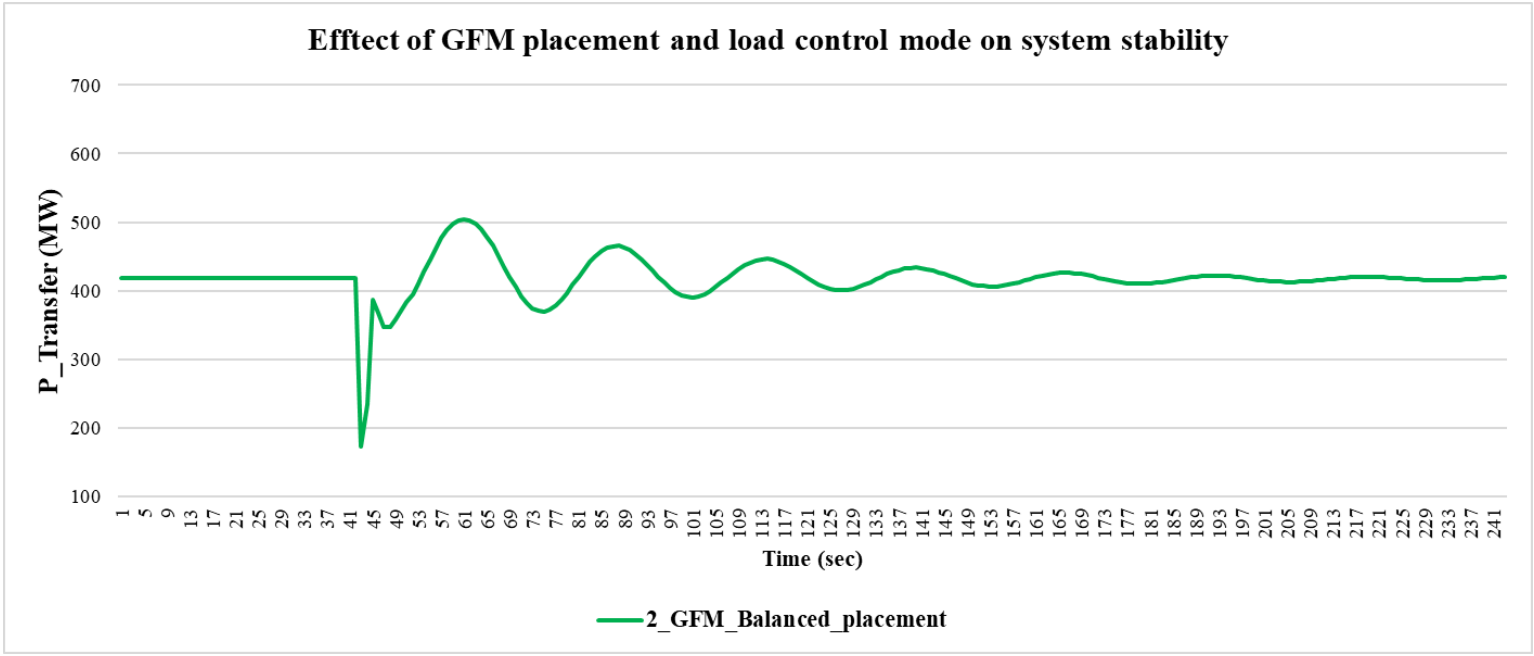
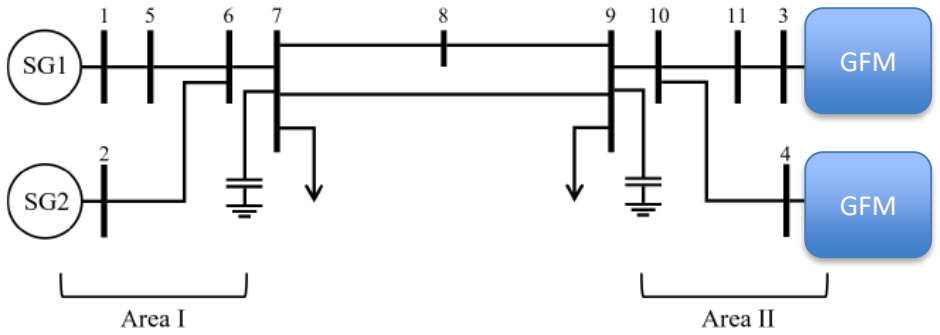
BALANCED PLACEMENT(DROOP BASED)



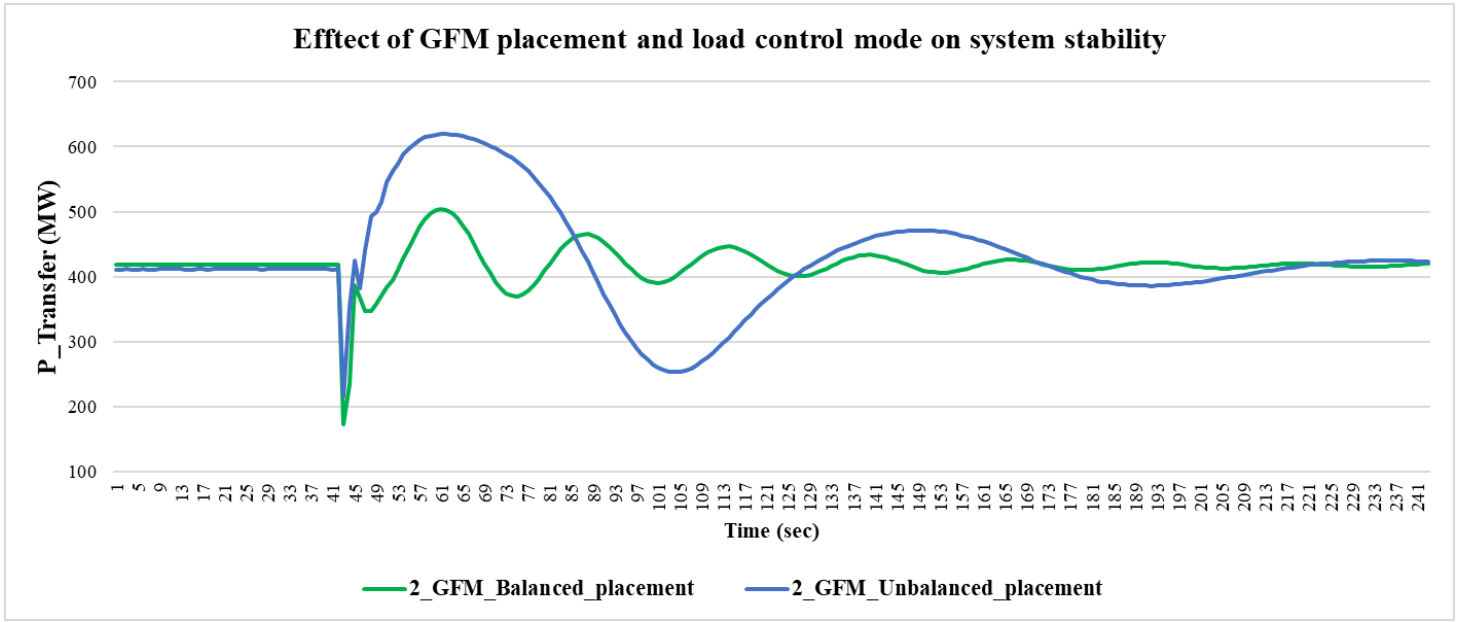
- No significant change in the mode of oscillation (same frequency)
- Higher damping



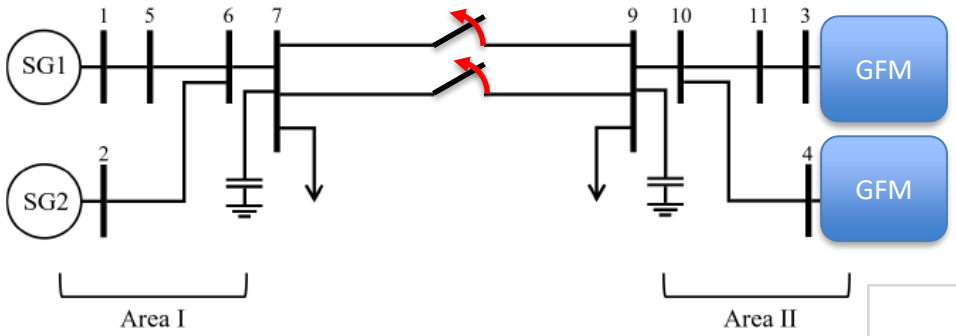
UNBALANCED PLACEMENT(DROOP BASED)

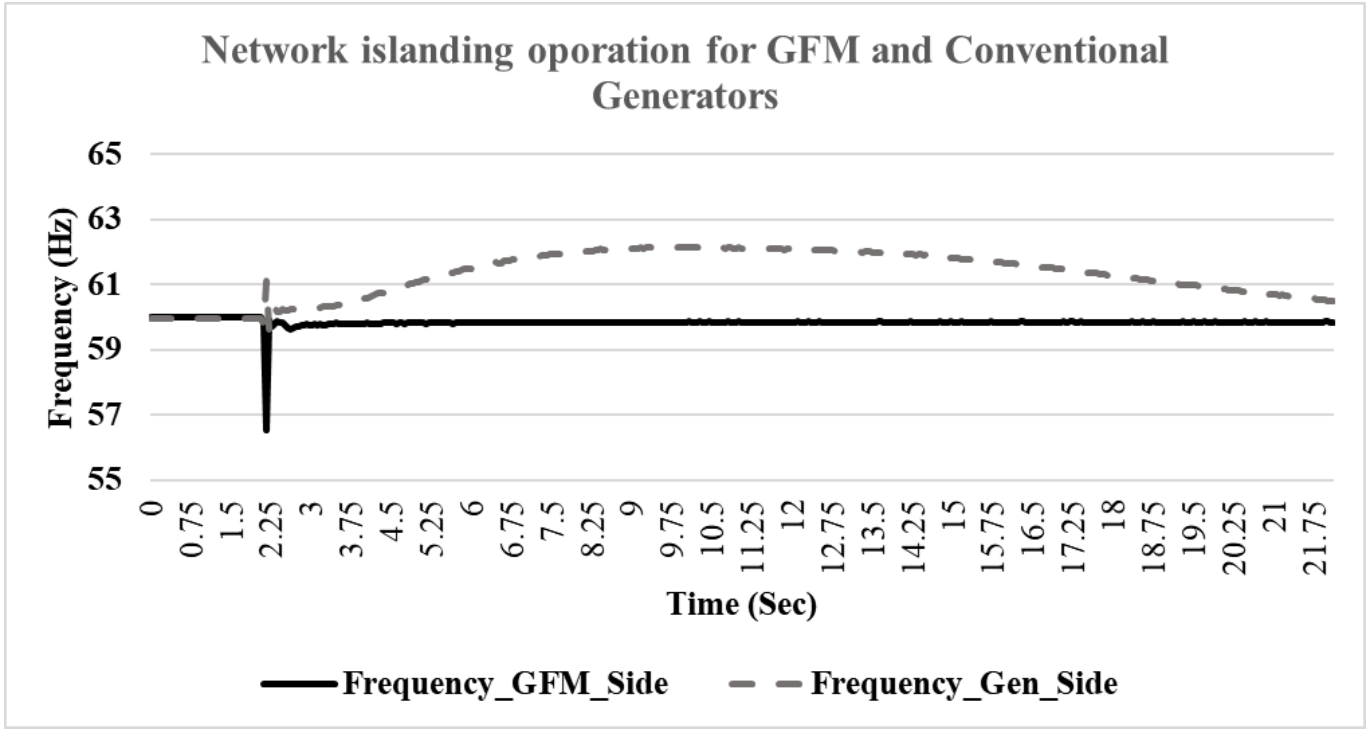


- Significant change to the modes of oscillation
- Require an adjustment to the existing stabilizers
- Conclusion: to maintain the existing system behavior for transition:
  - *VSM mode could be beneficial to maintain the system dynamic behavior*
  - *Mode shall be able to be switched in future to droop mode*
  - *If droop mode is selected, **small signal analysis** shall be done to ensure there is no adverse effect on PSS operation*



ISLANDED OPERATION





CONCLUSIONS AND RECOMMENDATIONS

- **Grid Forming Inverter VSM or Droop control modes**
- **Loads can do much more (Voltage support, frequency support, POD)**
- **Why expensive FACTS devises while Loads and Inverters can do the even better!**

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THANK YOU!

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